

# On Degenerations of Lie Superalgebras

Ma. Isabel Hernández

CONACYT - CIMAT Mérida

## Escola Latino Americana de Matematica

Universidade Federal do ABC, Santo André, S.P., Brasil, 2018





# Plan of the Talk

## Preliminaries

Algebras

Lie Algebras

The Variety  $\mathcal{L}ie_n$

## Lie superalgebras

Superalgebras

Lie Superalgebras

The Variety  $\mathcal{L}\mathcal{S}^{(m,n)}$

# Convention

Throughout this work all vector spaces are finite dimensional over a field  $\mathbb{F} = \mathbb{R}$  or  $\mathbb{F} = \mathbb{C}$ .

# Algebras

## Definition

An  $\mathbb{F}$ -algebra is a vector space  $A$  with a bilinear map

$$\cdot : A \times A \rightarrow A.$$

We say that  $A$  has a unit element if there is an element  $1 \in A$  such that

$$1 \cdot a = a \cdot 1 = a, \quad \text{for all } a \in A.$$

## Example

- ▶  $\mathbb{F}[x]$  is a commutative, associative algebra with unit.
- ▶ Let  $V$  a vector space.

$$\text{End}(V) = \{T : V \rightarrow V \mid T \text{ is linear}\}$$

is an associative algebra with unit (non-commutative).

# Algebras

## Definition

An  $\mathbb{F}$ -algebra is a vector space  $A$  with a bilinear map

$$\cdot : A \times A \rightarrow A.$$

We say that  $A$  has a unit element if there is an element  $1 \in A$  such that

$$1 \cdot a = a \cdot 1 = a, \quad \text{for all } a \in A.$$

## Example

- ▶  $\mathbb{F}[x]$  is a commutative, associative algebra with unit.
- ▶ Let  $V$  a vector space.

$$\text{End}(V) = \{T : V \rightarrow V \mid T \text{ is linear}\}$$

is an associative algebra with unit (non-commutative).

# Algebras

## Definition

An  $\mathbb{F}$ -algebra is a vector space  $A$  with a bilinear map

$$\cdot : A \times A \rightarrow A.$$

We say that  $A$  has a unit element if there is an element  $1 \in A$  such that

$$1 \cdot a = a \cdot 1 = a, \quad \text{for all } a \in A.$$

## Example

- ▶  $\mathbb{F}[x]$  is a commutative, associative algebra with unit.
- ▶ Let  $V$  a vector space.

$$\text{End}(V) = \{T : V \rightarrow V \mid T \text{ is linear}\}$$

is an associative algebra with unit (non-commutative).

# Algebras

## Definition

An  $\mathbb{F}$ -algebra is a vector space  $A$  with a bilinear map

$$\cdot : A \times A \rightarrow A.$$

We say that  $A$  has a unit element if there is an element  $1 \in A$  such that

$$1 \cdot a = a \cdot 1 = a, \quad \text{for all } a \in A.$$

## Example

- ▶  $\mathbb{F}[x]$  is a commutative, associative algebra with unit.
- ▶ Let  $V$  a vector space.

$$\text{End}(V) = \{T : V \rightarrow V \mid T \text{ is linear}\}$$

is an associative algebra with unit (non-commutative).



# Algebras

## Example

- ▶  $C^n(\mathbb{R}) : \{f : \mathbb{R} \rightarrow \mathbb{R} \mid f \text{ is } n\text{-times differentiable}\}, n \in \mathbb{N} \cup \{0\}$ .
- ▶  $\mathbb{R}^3$  with the cross product is a non-commutative, non-associative algebra without unit. In fact:

$$(e_1 \times e_2) \times e_2 \neq e_1 \times (e_2 \times e_2).$$

# Algebras

## Example

- ▶  $C^n(\mathbb{R}) : \{f : \mathbb{R} \rightarrow \mathbb{R} \mid f \text{ is } n\text{-times differentiable}\}, n \in \mathbb{N} \cup \{0\}$ .
- ▶  $\mathbb{R}^3$  with the cross product is a non-commutative, non-associative algebra without unit. In fact:

$$(e_1 \times e_2) \times e_2 \neq e_1 \times (e_2 \times e_2).$$

# Algebras

## Example

- ▶  $C^n(\mathbb{R}) : \{f : \mathbb{R} \rightarrow \mathbb{R} \mid f \text{ is } n\text{-times differentiable}\}$ ,  $n \in \mathbb{N} \cup \{0\}$ .
- ▶  $\mathbb{R}^3$  with the cross product is a non-commutative, non-associative algebra without unit. In fact:

$$(e_1 \times e_2) \times e_2 \neq e_1 \times (e_2 \times e_2).$$

## Algebras defined by identities

**Observation.** An Algebra  $A$  is

- ▶ commutative if  $xy = yx$ , for all  $x, y \in A$ , i.e.,

$$P_1(x, y) = xy - yx = 0, \quad \forall x, y \in A.$$

- ▶ associative if

$$P_2(x, y, z) = (xy)z - x(yz) = 0, \quad \forall x, y, z \in A.$$

**Notation.** Let  $V$  be an  $n$ -dimensional  $\mathbb{F}$ -vector space, and  $P_1, \dots, P_n$  polynomial identities.

$$\text{Alg}_n(P_1, \dots, P_r)$$

is the variety of algebras defined by  $P_1, \dots, P_n$ .

## Algebras defined by identities

**Observation.** An Algebra  $A$  is

- ▶ commutative if  $xy = yx$ , for all  $x, y \in A$ , i.e.,

$$P_1(x, y) = xy - yx = 0, \quad \forall x, y \in A.$$

- ▶ associative if

$$P_2(x, y, z) = (xy)z - x(yz) = 0, \quad \forall x, y, z \in A.$$

**Notation.** Let  $V$  be an  $n$ -dimensional  $\mathbb{F}$ -vector space, and  $P_1, \dots, P_n$  polynomial identities.

$$\text{Alg}_n(P_1, \dots, P_r)$$

is the variety of algebras defined by  $P_1, \dots, P_n$ .

## Algebras defined by identities

**Observation.** An Algebra  $A$  is

- ▶ commutative if  $xy = yx$ , for all  $x, y \in A$ , i.e.,

$$P_1(x, y) = xy - yx = 0, \quad \forall x, y \in A.$$

- ▶ associative if

$$P_2(x, y, z) = (xy)z - x(yz) = 0, \quad \forall x, y, z \in A.$$

**Notation.** Let  $V$  be an  $n$ -dimensional  $\mathbb{F}$ -vector space, and  $P_1, \dots, P_n$  polynomial identities.

$$\mathcal{Alg}_n(P_1, \dots, P_r)$$

is the variety of algebras defined by  $P_1, \dots, P_n$ .

## Algebras defined by identities

**Observation.** An Algebra  $A$  is

- ▶ commutative if  $xy = yx$ , for all  $x, y \in A$ , i.e.,

$$P_1(x, y) = xy - yx = 0, \quad \forall x, y \in A.$$

- ▶ associative if

$$P_2(x, y, z) = (xy)z - x(yz) = 0, \quad \forall x, y, z \in A.$$

**Notation.** Let  $V$  be an  $n$ -dimensional  $\mathbb{F}$ -vector space, and  $P_1, \dots, P_n$  polynomial identities.

$$\mathcal{Alg}_n(P_1, \dots, P_r)$$

is the variety of algebras defined by  $P_1, \dots, P_n$ .

## Algebras defined by identities

**Observation.** An Algebra  $A$  is

- ▶ commutative if  $xy = yx$ , for all  $x, y \in A$ , i.e.,

$$P_1(x, y) = xy - yx = 0, \quad \forall x, y \in A.$$

- ▶ associative if

$$P_2(x, y, z) = (xy)z - x(yz) = 0, \quad \forall x, y, z \in A.$$

**Notation.** Let  $V$  be an  $n$ -dimensional  $\mathbb{F}$ -vector space, and  $P_1, \dots, P_n$  polynomial identities.

$$\mathcal{Alg}_n(P_1, \dots, P_r)$$

is the variety of algebras defined by  $P_1, \dots, P_n$ .



# Lie Algebras

## Definition

An algebra  $\mathfrak{g}$ , with product  $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , is called a Lie algebra if:

(i)  $[x, y] = -[y, x]$  (antisymmetry),

(ii)  $[[x, y], z] + [[y, z], x] + [[z, x], y] = 0$  (Jacobi identity)

for all  $x, y, z \in \mathfrak{g}$ .

**Remark.** (i) is equivalent to the identity:  $x^2 = 0$ . From (ii) it follows that  $[\cdot, \cdot]$  is non-associative. Moreover, a Lie algebra is abelian if and only if  $[\cdot, \cdot] = 0$ .

## Example

- ▶ Every vector space  $V$  is a Lie algebra taking  $[\cdot, \cdot] = 0$ . It is called the abelian Lie algebra.
- ▶ The cross product  $(\mathbb{R}^3, \times)$  is a Lie algebra.

# Lie Algebras

## Definition

An algebra  $\mathfrak{g}$ , with product  $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , is called a Lie algebra if:

- (i)  $[x, y] = -[y, x]$  (antisymmetry),
- (ii)  $[[x, y], z] + [[y, z], x] + [[z, x], y] = 0$  (Jacobi identity)

for all  $x, y, z \in \mathfrak{g}$ .

**Remark.** (i) is equivalent to the identity:  $x^2 = 0$ , From (ii) it follows that  $[\cdot, \cdot]$  is non-associative. Moreover, a Lie algebra is abelian if and only if  $[\cdot, \cdot] = 0$ .

## Example

- ▶ Every vector space  $V$  is a Lie algebra taking  $[\cdot, \cdot] = 0$ . It is called the abelian Lie algebra.
- ▶ The cross product  $(\mathbb{R}^3, \times)$  is a Lie algebra.

# Lie Algebras

## Definition

An algebra  $\mathfrak{g}$ , with product  $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , is called a Lie algebra if:

- (i)  $[x, y] = -[y, x]$  (antisymmetry),
- (ii)  $[[x, y], z] + [[y, z], x] + [[z, x], y] = 0$  (Jacobi identity)

for all  $x, y, z \in \mathfrak{g}$ .

**Remark.** (i) is equivalent to the identity:  $x^2 = 0$ , From (ii) it follows that  $[\cdot, \cdot]$  is non-associative. Moreover, a Lie algebra is abelian if and only if  $[\cdot, \cdot] = 0$ .

## Example

- ▶ Every vector space  $V$  is a Lie algebra taking  $[\cdot, \cdot] = 0$ . It is called the abelian Lie algebra.
- ▶ The cross product  $(\mathbb{R}^3, \times)$  is a Lie algebra.

# Lie Algebras

## Definition

An algebra  $\mathfrak{g}$ , with product  $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , is called a Lie algebra if:

- (i)  $[x, y] = -[y, x]$  (antisymmetry),
- (ii)  $[[x, y], z] + [[y, z], x] + [[z, x], y] = 0$  (Jacobi identity)

for all  $x, y, z \in \mathfrak{g}$ .

**Remark.** (i) is equivalent to the identity:  $x^2 = 0$ , From (ii) it follows that  $[\cdot, \cdot]$  is non-associative. Moreover, a Lie algebra is abelian if and only if  $[\cdot, \cdot] = 0$ .

## Example

- ▶ Every vector space  $V$  is a Lie algebra taking  $[\cdot, \cdot] = 0$ . It is called the abelian Lie algebra.
- ▶ The cross product  $(\mathbb{R}^3, \times)$  is a Lie algebra.

# Lie Algebras

## Definition

An algebra  $\mathfrak{g}$ , with product  $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , is called a Lie algebra if:

- (i)  $[x, y] = -[y, x]$  (antisymmetry),
- (ii)  $[[x, y], z] + [[y, z], x] + [[z, x], y] = 0$  (Jacobi identity)

for all  $x, y, z \in \mathfrak{g}$ .

**Remark.** (i) is equivalent to the identity:  $x^2 = 0$ , From (ii) it follows that  $[\cdot, \cdot]$  is non-associative. Moreover, a Lie algebra is abelian if and only if  $[\cdot, \cdot] = 0$ .

## Example

- ▶ Every vector space  $V$  is a Lie algebra taking  $[\cdot, \cdot] = 0$ . It is called the abelian Lie algebra.
- ▶ The cross product  $(\mathbb{R}^3, \times)$  is a Lie algebra.

# Lie Algebras

## Definition

An algebra  $\mathfrak{g}$ , with product  $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , is called a Lie algebra if:

- (i)  $[x, y] = -[y, x]$  (antisymmetry),
- (ii)  $[[x, y], z] + [[y, z], x] + [[z, x], y] = 0$  (Jacobi identity)

for all  $x, y, z \in \mathfrak{g}$ .

**Remark.** (i) is equivalent to the identity:  $x^2 = 0$ , From (ii) it follows that  $[\cdot, \cdot]$  is non-associative. Moreover, a Lie algebra is abelian if and only if  $[\cdot, \cdot] = 0$ .

## Example

- ▶ Every vector space  $V$  is a Lie algebra taking  $[\cdot, \cdot] = 0$ . It is called the abelian Lie algebra.
- ▶ The cross product  $(\mathbb{R}^3, \times)$  is a Lie algebra.

# Lie Algebras

## Definition

An algebra  $\mathfrak{g}$ , with product  $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , is called a Lie algebra if:

- (i)  $[x, y] = -[y, x]$  (antisymmetry),
- (ii)  $[[x, y], z] + [[y, z], x] + [[z, x], y] = 0$  (Jacobi identity)

for all  $x, y, z \in \mathfrak{g}$ .

**Remark.** (i) is equivalent to the identity:  $x^2 = 0$ , From (ii) it follows that  $[\cdot, \cdot]$  is non-associative. Moreover, a Lie algebra is abelian if and only if  $[\cdot, \cdot] = 0$ .

## Example

- ▶ Every vector space  $V$  is a Lie algebra taking  $[\cdot, \cdot] = 0$ . It is called the abelian Lie algebra.
- ▶ The cross product  $(\mathbb{R}^3, \times)$  is a Lie algebra.

# Lie Algebras

## Definition

An algebra  $\mathfrak{g}$ , with product  $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , is called a Lie algebra if:

- (i)  $[x, y] = -[y, x]$  (antisymmetry),
- (ii)  $[[x, y], z] + [[y, z], x] + [[z, x], y] = 0$  (Jacobi identity)

for all  $x, y, z \in \mathfrak{g}$ .

**Remark.** (i) is equivalent to the identity:  $x^2 = 0$ , From (ii) it follows that  $[\cdot, \cdot]$  is non-associative. Moreover, a Lie algebra is abelian if and only if  $[\cdot, \cdot] = 0$ .

## Example

- ▶ Every vector space  $V$  is a Lie algebra taking  $[\cdot, \cdot] = 0$ . It is called the abelian Lie algebra.
- ▶ The cross product  $(\mathbb{R}^3, \times)$  is a Lie algebra.



# Lie Algebras

## Definition

An algebra  $\mathfrak{g}$ , with product  $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , is called a Lie algebra if:

- (i)  $[x, y] = -[y, x]$  (antisymmetry),
- (ii)  $[[x, y], z] + [[y, z], x] + [[z, x], y] = 0$  (Jacobi identity)

for all  $x, y, z \in \mathfrak{g}$ .

**Remark.** (i) is equivalent to the identity:  $x^2 = 0$ , From (ii) it follows that  $[\cdot, \cdot]$  is non-associative. Moreover, a Lie algebra is abelian if and only if  $[\cdot, \cdot] = 0$ .

## Example

- ▶ Every vector space  $V$  is a Lie algebra taking  $[\cdot, \cdot] = 0$ . It is called the abelian Lie algebra.
- ▶ The cross product  $(\mathbb{R}^3, \times)$  is a Lie algebra.

# Lie Algebras

## Examples

- ▶ **The General Linear Lie Algebra**  $\mathfrak{gl}(V)$ . Let  $V$  an  $\mathbb{F}$ -vector space. Define:

$$[T, S] = T \circ S - S \circ T, \quad T, S \in \text{End}(V).$$

Notation:  $\mathfrak{gl}(V) = (\text{End}(V), [\cdot, \cdot])$ .

- ▶ **The Special Linear Lie Algebra**  $\mathfrak{sl}(V)$ .

$$\mathfrak{sl}(V) = \{T \in \text{End}(V) : \text{tr}(T) = 0\} \subset \mathfrak{gl}(V).$$

- ▶ Let  $\mathcal{B} : V \times V \rightarrow \mathbb{F}$  be a bilinear form.

$$\mathfrak{gl}(V)_{\mathcal{B}} = \{T \in \text{End}(V) : \mathcal{B}(T(u), v) + \mathcal{B}(u, T(v)) = 0\}$$

is a subalgebra of  $\mathfrak{gl}(V)$ .

# Lie Algebras

## Examples

- ▶ **The General Linear Lie Algebra**  $\mathfrak{gl}(V)$ . Let  $V$  an  $\mathbb{F}$ -vector space. Define:

$$[T, S] = T \circ S - S \circ T, \quad T, S \in \text{End}(V).$$

Notation:  $\mathfrak{gl}(V) = (\text{End}(V), [\cdot, \cdot])$ .

- ▶ **The Special Linear Lie Algebra**  $\mathfrak{sl}(V)$ .

$$\mathfrak{sl}(V) = \{T \in \text{End}(V) : \text{tr}(T) = 0\} \subset \mathfrak{gl}(V).$$

- ▶ Let  $\mathcal{B} : V \times V \rightarrow \mathbb{F}$  be a bilinear form.

$$\mathfrak{gl}(V)_{\mathcal{B}} = \{T \in \text{End}(V) : \mathcal{B}(T(u), v) + \mathcal{B}(u, T(v)) = 0\}$$

is a subalgebra of  $\mathfrak{gl}(V)$ .

# Lie Algebras

## Examples

- ▶ **The General Linear Lie Algebra**  $\mathfrak{gl}(V)$ . Let  $V$  an  $\mathbb{F}$ -vector space. Define:

$$[T, S] = T \circ S - S \circ T, \quad T, S \in \text{End}(V).$$

Notation:  $\mathfrak{gl}(V) = (\text{End}(V), [\cdot, \cdot])$ .

- ▶ **The Special Linear Lie Algebra**  $\mathfrak{sl}(V)$ .

$$\mathfrak{sl}(V) = \{T \in \text{End}(V) : \text{tr}(T) = 0\} \subset \mathfrak{gl}(V).$$

- ▶ Let  $\mathcal{B} : V \times V \rightarrow \mathbb{F}$  be a bilinear form.

$$\mathfrak{gl}(V)_{\mathcal{B}} = \{T \in \text{End}(V) : \mathcal{B}(T(u), v) + \mathcal{B}(u, T(v)) = 0\}$$

is a subalgebra of  $\mathfrak{gl}(V)$ .

# Lie Algebras

## Examples

- ▶ **The General Linear Lie Algebra**  $\mathfrak{gl}(V)$ . Let  $V$  an  $\mathbb{F}$ -vector space. Define:

$$[T, S] = T \circ S - S \circ T, \quad T, S \in \text{End}(V).$$

Notation:  $\mathfrak{gl}(V) = (\text{End}(V), [\cdot, \cdot])$ .

- ▶ **The Special Linear Lie Algebra**  $\mathfrak{sl}(V)$ .

$$\mathfrak{sl}(V) = \{T \in \text{End}(V) : \text{tr}(T) = 0\} \subset \mathfrak{gl}(V).$$

- ▶ Let  $\mathcal{B} : V \times V \rightarrow \mathbb{F}$  be a bilinear form.

$$\mathfrak{gl}(V)_{\mathcal{B}} = \{T \in \text{End}(V) : \mathcal{B}(T(u), v) + \mathcal{B}(u, T(v)) = 0\}$$

is a subalgebra of  $\mathfrak{gl}(V)$ .

# Lie Algebras

## Examples

- ▶ **The General Linear Lie Algebra**  $\mathfrak{gl}(V)$ . Let  $V$  an  $\mathbb{F}$ -vector space. Define:

$$[T, S] = T \circ S - S \circ T, \quad T, S \in \text{End}(V).$$

Notation:  $\mathfrak{gl}(V) = (\text{End}(V), [\cdot, \cdot])$ .

- ▶ **The Special Linear Lie Algebra**  $\mathfrak{sl}(V)$ .

$$\mathfrak{sl}(V) = \{T \in \text{End}(V) : \text{tr}(T) = 0\} \subset \mathfrak{gl}(V).$$

- ▶ Let  $\mathcal{B} : V \times V \rightarrow \mathbb{F}$  be a bilinear form.

$$\mathfrak{gl}(V)_{\mathcal{B}} = \{T \in \text{End}(V) : \mathcal{B}(T(u), v) + \mathcal{B}(u, T(v)) = 0\}$$

is a subalgebra of  $\mathfrak{gl}(V)$ .

# Lie Algebras

## Examples

- ▶ **The General Linear Lie Algebra**  $\mathfrak{gl}(V)$ . Let  $V$  an  $\mathbb{F}$ -vector space. Define:

$$[T, S] = T \circ S - S \circ T, \quad T, S \in \text{End}(V).$$

Notation:  $\mathfrak{gl}(V) = (\text{End}(V), [\cdot, \cdot])$ .

- ▶ **The Special Linear Lie Algebra**  $\mathfrak{sl}(V)$ .

$$\mathfrak{sl}(V) = \{T \in \text{End}(V) : \text{tr}(T) = 0\} \subset \mathfrak{gl}(V).$$

- ▶ Let  $\mathcal{B} : V \times V \rightarrow \mathbb{F}$  be a bilinear form.

$$\mathfrak{gl}(V)_{\mathcal{B}} = \{T \in \text{End}(V) : \mathcal{B}(T(\mathbf{u}), \mathbf{v}) + \mathcal{B}(\mathbf{u}, T(\mathbf{v})) = 0\}$$

is a subalgebra of  $\mathfrak{gl}(V)$ .

# Lie Algebras

## Definition

A morphism of Lie algebras  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$  is a linear map such that

$$\phi[x, y]_{\mathfrak{g}} = [\phi(x), \phi(y)]_{\mathfrak{h}}, \quad x, y \in \mathfrak{g}.$$

The Lie algebras  $\mathfrak{g}$  and  $\mathfrak{h}$  are isomorphic if there exists a bijective morphism  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$ .

## Example

- ▶  $(\mathbb{R}^3, \times) \simeq \mathfrak{gl}(\mathbb{R}^2)_{\mathcal{B}}$ , where  $\mathcal{B} : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$

$$\mathcal{B} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

- ▶ Let  $V$  a vector space. A morphism  $\rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$  is called a representation.



# Lie Algebras

## Definition

A morphism of Lie algebras  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$  is a linear map such that

$$\phi[x, y]_{\mathfrak{g}} = [\phi(x), \phi(y)]_{\mathfrak{h}}, \quad x, y \in \mathfrak{g}.$$

The Lie algebras  $\mathfrak{g}$  and  $\mathfrak{h}$  are isomorphic if there exists a bijective morphism  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$ .

## Example

- ▶  $(\mathbb{R}^3, \times) \simeq \mathfrak{gl}(\mathbb{R}^2)_{\mathcal{B}}$ , where  $\mathcal{B} : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$

$$\mathcal{B} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

- ▶ Let  $V$  a vector space. A morphism  $\rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$  is called a representation.

# Lie Algebras

## Definition

A morphism of Lie algebras  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$  is a linear map such that

$$\phi[x, y]_{\mathfrak{g}} = [\phi(x), \phi(y)]_{\mathfrak{h}}, \quad x, y \in \mathfrak{g}.$$

The Lie algebras  $\mathfrak{g}$  and  $\mathfrak{h}$  are isomorphic if there exists a bijective morphism  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$ .

## Example

- ▶  $(\mathbb{R}^3, \times) \simeq \mathfrak{gl}(\mathbb{R}^2)_{\mathcal{B}}$ , where  $\mathcal{B} : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$

$$\mathcal{B} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

- ▶ Let  $V$  a vector space. A morphism  $\rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$  is called a representation.

# Lie Algebras

## Definition

A morphism of Lie algebras  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$  is a linear map such that

$$\phi[x, y]_{\mathfrak{g}} = [\phi(x), \phi(y)]_{\mathfrak{h}}, \quad x, y \in \mathfrak{g}.$$

The Lie algebras  $\mathfrak{g}$  and  $\mathfrak{h}$  are isomorphic if there exists a bijective morphism  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$ .

## Example

- ▶  $(\mathbb{R}^3, \times) \simeq \mathfrak{gl}(\mathbb{R}^2)_{\mathcal{B}}$ , where  $\mathcal{B} : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$

$$\mathcal{B} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

- ▶ Let  $V$  a vector space. A morphism  $\rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$  is called a representation.

# Lie Algebras

## Definition

A morphism of Lie algebras  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$  is a linear map such that

$$\phi[x, y]_{\mathfrak{g}} = [\phi(x), \phi(y)]_{\mathfrak{h}}, \quad x, y \in \mathfrak{g}.$$

The Lie algebras  $\mathfrak{g}$  and  $\mathfrak{h}$  are isomorphic if there exists a bijective morphism  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$ .

## Example

- ▶  $(\mathbb{R}^3, \times) \simeq \mathfrak{gl}(\mathbb{R}^2)_{\mathcal{B}}$ , where  $\mathcal{B} : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$

$$\mathcal{B} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

- ▶ Let  $V$  a vector space. A morphism  $\rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$  is called a representation.

# Lie Algebras

## Definition

A morphism of Lie algebras  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$  is a linear map such that

$$\phi[x, y]_{\mathfrak{g}} = [\phi(x), \phi(y)]_{\mathfrak{h}}, \quad x, y \in \mathfrak{g}.$$

The Lie algebras  $\mathfrak{g}$  and  $\mathfrak{h}$  are isomorphic if there exists a bijective morphism  $\phi : \mathfrak{g} \rightarrow \mathfrak{h}$ .

## Example

- ▶  $(\mathbb{R}^3, \times) \simeq \mathfrak{gl}(\mathbb{R}^2)_{\mathcal{B}}$ , where  $\mathcal{B} : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$

$$\mathcal{B} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

- ▶ Let  $V$  a vector space. A morphism  $\rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$  is called a representation.

# Associative $\leftrightarrow$ Lie

## Example

Let  $(A, \cdot)$  be an associative algebra. Define a new product by

$$[a, b] = a \cdot b - b \cdot a, \quad a, b \in A.$$

Then,  $A^- = (A, [\cdot, \cdot])$  is a Lie algebra.

## Theorem (Poincaré-Birkhoff-Witt)

*Let  $\mathfrak{g}$  be a Lie algebra, then  $\mathfrak{g}$  is isomorphic to  $A^-$  for some associative algebra  $A$ .*

# Associative $\leftrightarrow$ Lie

## Example

Let  $(A, \cdot)$  be an associative algebra. Define a new product by

$$[a, b] = a \cdot b - b \cdot a, \quad a, b \in A.$$

Then,  $A^- = (A, [\cdot, \cdot])$  is a Lie algebra.

## Theorem (Poincaré-Birkhoff-Witt)

*Let  $\mathfrak{g}$  be a Lie algebra, then  $\mathfrak{g}$  is isomorphic to  $A^-$  for some associative algebra  $A$ .*

# Associative $\leftrightarrow$ Lie

## Example

Let  $(A, \cdot)$  be an associative algebra. Define a new product by

$$[a, b] = a \cdot b - b \cdot a, \quad a, b \in A.$$

Then,  $A^- = (A, [\cdot, \cdot])$  is a Lie algebra.

## Theorem (Poincaré-Birkhoff-Witt)

*Let  $\mathfrak{g}$  be a Lie algebra, then  $\mathfrak{g}$  is isomorphic to  $A^-$  for some associative algebra  $A$ .*



# Associative $\leftrightarrow$ Lie

## Example

Let  $(A, \cdot)$  be an associative algebra. Define a new product by

$$[a, b] = a \cdot b - b \cdot a, \quad a, b \in A.$$

Then,  $A^- = (A, [\cdot, \cdot])$  is a Lie algebra.

## Theorem (Poincaré-Birkhoff-Witt)

*Let  $\mathfrak{g}$  be a Lie algebra, then  $\mathfrak{g}$  is isomorphic to  $A^-$  for some associative algebra  $A$ .*

# Associative $\leftrightarrow$ Lie

## Example

Let  $(A, \cdot)$  be an associative algebra. Define a new product by

$$[a, b] = a \cdot b - b \cdot a, \quad a, b \in A.$$

Then,  $A^- = (A, [\cdot, \cdot])$  is a Lie algebra.

## Theorem (Poincaré-Birkhoff-Witt)

*Let  $\mathfrak{g}$  be a Lie algebra, then  $\mathfrak{g}$  is isomorphic to  $A^-$  for some associative algebra  $A$ .*

# Structure Constants of a Lie Algebra

Let  $\mathfrak{g}$  be a Lie algebra with product  $[\cdot, \cdot]$ , and let  $\{e_1, \dots, e_n\}$  be a basis for  $\mathfrak{g}$ .

Notice that:

$$[x, y] = \sum_{i,j} x_i y_j [e_i, e_j], \quad x, y \in \mathfrak{g}.$$

Write

$$[e_i, e_j] = \sum_{k=1}^n c_{ij}^k e_k. \quad i, j \in \{1, \dots, n\}.$$

## Definition

The set  $\{c_{ij}^k\} \subset F$  is called the set of structure constants of  $\mathfrak{g}$  respect to the basis  $\{e_i\}_{i=1}^n$ .

# Structure Constants of a Lie Algebra

Let  $\mathfrak{g}$  be a Lie algebra with product  $[\cdot, \cdot]$ , and let  $\{e_1, \dots, e_n\}$  be a basis for  $\mathfrak{g}$ . Notice that:

$$[x, y] = \sum_{i,j} x_i y_j [e_i, e_j], \quad x, y \in \mathfrak{g}.$$

Write

$$[e_i, e_j] = \sum_{k=1}^n c_{ij}^k e_k. \quad i, j \in \{1, \dots, n\}.$$

## Definition

The set  $\{c_{ij}^k\} \subset F$  is called the set of structure constants of  $\mathfrak{g}$  respect to the basis  $\{e_i\}_{i=1}^n$ .

# Structure Constants of a Lie Algebra

Let  $\mathfrak{g}$  be a Lie algebra with product  $[\cdot, \cdot]$ , and let  $\{e_1, \dots, e_n\}$  be a basis for  $\mathfrak{g}$ . Notice that:

$$[x, y] = \sum_{i,j} x_i y_j [e_i, e_j], \quad x, y \in \mathfrak{g}.$$

Write

$$[e_i, e_j] = \sum_{k=1}^n c_{ij}^k e_k. \quad i, j \in \{1, \dots, n\}.$$

## Definition

The set  $\{c_{ij}^k\} \subset F$  is called the set of structure constants of  $\mathfrak{g}$  respect to the basis  $\{e_i\}_{i=1}^n$ .

# Structure Constants of a Lie Algebra

Let  $\mathfrak{g}$  be a Lie algebra with product  $[\cdot, \cdot]$ , and let  $\{e_1, \dots, e_n\}$  be a basis for  $\mathfrak{g}$ . Notice that:

$$[x, y] = \sum_{i,j} x_i y_j [e_i, e_j], \quad x, y \in \mathfrak{g}.$$

Write

$$[e_i, e_j] = \sum_{k=1}^n c_{ij}^k e_k. \quad i, j \in \{1, \dots, n\}.$$

## Definition

The set  $\{c_{ij}^k\} \subset F$  is called the set of structure constants of  $\mathfrak{g}$  respect to the basis  $\{e_i\}_{i=1}^n$ .

# Structure Constants of a Lie Algebra

**Remark.** Notice that

- ▶ From the skew symmetry:

$$c_{ij}^k + c_{ji}^k = 0, \quad \text{for all } i, j, k \in \{1, \dots, n\}.$$

- ▶ From the Jacobi identity;

$$\sum_{l=1}^n c_{ij}^l c_{lk}^m + c_{ki}^l c_{lj}^m + c_{jk}^l c_{li}^m = 0,$$

for all  $i, j, k, m \in \{1, \dots, n\}$ .

$$\mathfrak{g} \longleftrightarrow (c_{ij}^k) \in \mathbb{F}^{\frac{n^3-n^2}{2}}$$

# Structure Constants of a Lie Algebra

**Remark.** Notice that

- ▶ From the skew symmetry:

$$c_{ij}^k + c_{ji}^k = 0, \quad \text{for all } i, j, k \in \{1, \dots, n\}.$$

- ▶ From the Jacobi identity;

$$\sum_{l=1}^n c_{ij}^l c_{lk}^m + c_{ki}^l c_{lj}^m + c_{jk}^l c_{li}^m = 0,$$

for all  $i, j, k, m \in \{1, \dots, n\}$ .

$$\mathfrak{g} \longleftrightarrow (c_{ij}^k) \in \mathbb{F}^{\frac{n^3-n^2}{2}}$$



# Structure Constants of a Lie Algebra

**Remark.** Notice that

- ▶ From the skew symmetry:

$$c_{ij}^k + c_{ji}^k = 0, \quad \text{for all } i, j, k \in \{1, \dots, n\}.$$

- ▶ From the Jacobi identity;

$$\sum_{l=1}^n c_{ij}^l c_{lk}^m + c_{ki}^l c_{lj}^m + c_{jk}^l c_{li}^m = 0,$$

for all  $i, j, k, m \in \{1, \dots, n\}$ .

$$\mathfrak{g} \longleftrightarrow (c_{ij}^k) \in \mathbb{F}^{\frac{n^3-n^2}{2}}$$

# Structure Constants of a Lie Algebra

**Remark.** Notice that

- ▶ From the skew symmetry:

$$c_{ij}^k + c_{ji}^k = 0, \quad \text{for all } i, j, k \in \{1, \dots, n\}.$$

- ▶ From the Jacobi identity;

$$\sum_{l=1}^n c_{ij}^l c_{lk}^m + c_{ki}^l c_{lj}^m + c_{jk}^l c_{li}^m = 0,$$

for all  $i, j, k, m \in \{1, \dots, n\}$ .

$$\mathfrak{g} \longleftrightarrow (c_{ij}^k) \in \mathbb{F}^{\frac{n^3-n^2}{2}}$$

# The Variety $\mathcal{L}ie_n$

If

$$(i) \quad P_1((x_{ij}^k)) = x_{ij}^k + x_{ji}^k,$$

$$(ii) \quad P_2((x_{ij}^k)) = \sum_{l=1}^n x_{ij}^l x_{lk}^m + x_{ki}^l x_{lj}^m + x_{jk}^l x_{li}^m,$$

then

$$\mathcal{L}ie_n = \mathcal{A}lg_n(P_1, P_2) \subset A^{n^3}$$

is a variety where every point represent a Lie algebra.

# Structure Constants in general

Let  $V$  be an  $n$ -dimensional  $\mathbb{F}$ -vector space and let  $\{e_1, \dots, e_n\}$  be a fixed basis for  $V$ . Given an algebra  $A = (V, \cdot)$  we write

$$e_i \cdot e_j = \sum_{k=1}^n x_{ij}^k e_k, \quad i, j = 1, \dots, n,$$

$\{x_{ij}^k\} \subset \mathbb{F}$  is the set of structure constants of  $A$  respect to the basis  $\{e_1, \dots, e_n\}$ .

## Structure Constants in general

Let  $V$  be an  $n$ -dimensional  $\mathbb{F}$ -vector space and let  $\{e_1, \dots, e_n\}$  be a fixed basis for  $V$ . Given an algebra  $A = (V, \cdot)$  we write

$$e_i \cdot e_j = \sum_{k=1}^n x_{ij}^k e_k, \quad i, j = 1, \dots, n,$$

$\{x_{ij}^k\} \subset \mathbb{F}$  is the set of structure constants of  $A$  respect to the basis  $\{e_1, \dots, e_n\}$ .

# The Variety $\mathcal{A}lg_n(P_1, \dots, P_r)$

Let  $A = (V, \cdot)$  be an algebra defined by the polynomial identities  $P_1, \dots, P_r$ . Then its set of structure constants must satisfy these identities.

$$\left\{ \begin{array}{l} \text{Algebras over } V \\ \text{satisfying } P_1, \dots, P_r \end{array} \right\} \longleftrightarrow \mathcal{A}lg_n(P_1, \dots, P_r) \subset \mathbb{A}^{n^3} \quad \text{affine variety}$$

$$(A, \cdot) \longleftrightarrow (x_{ij}^k)$$

# The Variety $\mathcal{Alg}_n(P_1, \dots, P_r)$

Let  $A = (V, \cdot)$  be an algebra defined by the polynomial identities  $P_1, \dots, P_r$ . Then its set of structure constants must satisfy these identities.

$$\left\{ \begin{array}{l} \text{Algebras over } V \\ \text{satisfying } P_1, \dots, P_r \end{array} \right\} \longleftrightarrow \mathcal{Alg}_n(P_1, \dots, P_r) \subset \mathbb{A}^{n^3} \quad \text{affine variety}$$

$$(A, \cdot) \longleftrightarrow (x_{ij}^k)$$

# Change of basis

Given a  $\mathbb{F}$ -vector space  $V$  with fixed basis  $\{e_i\}_{i=1}^n$ , we have

$$\left\{ \begin{array}{l} \text{Algebras over } V \\ \text{satisfying } P_1, \dots, P_r \end{array} \right\} \longleftrightarrow \text{Alg}_n(P_1, \dots, P_r) \subset \mathbb{A}^{n^3}$$



What happens if we change the basis of  $V$ ?

# Change of basis

## Lemma

There is an action of  $G = GL(\mathbb{F}^n)$  on  $\mathcal{L}ie_n$  given by “change of basis”

$$g \cdot [\cdot, \cdot] = [\cdot, \cdot]' = g[g^{-1}(\cdot), g^{-1}(\cdot)].$$

where

- (i) The  $G$ -orbits are in one-to-one correspondence with the isomorphism classes.
- (ii)  $\text{Stab}_G([\cdot, \cdot]) \longleftrightarrow \text{Aut}([\cdot, \cdot])$ .

# Change of basis

## Lemma

There is an action of  $G = GL(\mathbb{F}^n)$  on  $\mathcal{L}ie_n$  given by “change of basis”

$$g \cdot [\cdot, \cdot] = [\cdot, \cdot]' = g[g^{-1}(\cdot), g^{-1}(\cdot)].$$

where

- (i) The  $G$ -orbits are in one-to-one correspondence with the isomorphism classes.
- (ii)  $\text{Stab}_G([\cdot, \cdot]) \longleftrightarrow \text{Aut}([\cdot, \cdot])$ .

# Change of basis

## Lemma

There is an action of  $G = \mathrm{GL}(\mathbb{F}^n)$  on  $\mathcal{L}ie_n$  given by “change of basis”

$$g \cdot [\cdot, \cdot] = [\cdot, \cdot]' = g[g^{-1}(\cdot), g^{-1}(\cdot)].$$

where

- (i) The  $G$ -orbits are in one-to-one correspondence with the isomorphism classes.
- (ii)  $\mathrm{Stab}_G([\cdot, \cdot]) \longleftrightarrow \mathrm{Aut}([\cdot, \cdot])$ .

# Change of basis

## Lemma

There is an action of  $G = \mathrm{GL}(\mathbb{F}^n)$  on  $\mathcal{L}ie_n$  given by “change of basis”

$$g \cdot [\cdot, \cdot] = [\cdot, \cdot]' = g[g^{-1}(\cdot), g^{-1}(\cdot)].$$

where

- (i) The  $G$ -orbits are in one-to-one correspondence with the isomorphism classes.
- (ii)  $\mathrm{Stab}_G([\cdot, \cdot]) \longleftrightarrow \mathrm{Aut}([\cdot, \cdot])$ .

# Change of basis

## Lemma

There is an action of  $G = GL(\mathbb{F}^n)$  on  $\mathcal{L}ie_n$  given by “change of basis”

$$g \cdot [\cdot, \cdot] = [\cdot, \cdot]' = g[g^{-1}(\cdot), g^{-1}(\cdot)].$$

where

- (i) The  $G$ -orbits are in one-to-one correspondence with the isomorphism classes.
- (ii)  $\text{Stab}_G([\cdot, \cdot]) \longleftrightarrow \text{Aut}([\cdot, \cdot])$ .

# Interesting Problems

(Recall  $G = GL(\mathbb{F}^n)$ )

Given the action “change of basis”

$$G \times \mathcal{L}ie_n \rightarrow \mathcal{L}ie_n$$

- (i) To find the  $G$ -orbits.
- (ii) To find the Zariski closure of every  $G$ -orbit.

## Definition

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{L}ie_n$ . We say that  $\mathfrak{g}$  degenerates to  $\mathfrak{h}$  ( $\mathfrak{g} \rightarrow \mathfrak{h}$ ) if

$$\mathfrak{h} \in \overline{G \cdot \mathfrak{g}}$$

# Interesting Problems

(Recall  $G = GL(\mathbb{F}^n)$ )

Given the action “change of basis”

$$G \times \mathcal{L}ie_n \rightarrow \mathcal{L}ie_n$$

- (i) To find the  $G$ -orbits.
- (ii) To find the Zariski closure of every  $G$ -orbit.

## Definition

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{L}ie_n$ . We say that  $\mathfrak{g}$  degenerates to  $\mathfrak{h}$  ( $\mathfrak{g} \rightarrow \mathfrak{h}$ ) if

$$\mathfrak{h} \in \overline{G \cdot \mathfrak{g}}$$



# Interesting Problems

(Recall  $G = GL(\mathbb{F}^n)$ )

Given the action “change of basis”

$$G \times \mathcal{L}ie_n \rightarrow \mathcal{L}ie_n$$

- (i) To find the  $G$ -orbits.
- (ii) To find the Zariski closure of every  $G$ -orbit.

## Definition

Let  $g, h \in \mathcal{L}ie_n$ . We say that  $g$  degenerates to  $h$  ( $g \rightarrow h$ ) if

$$h \in \overline{G \cdot g}$$

# Interesting Problems

(Recall  $G = GL(\mathbb{F}^n)$ )

Given the action “change of basis”

$$G \times \mathcal{L}ie_n \rightarrow \mathcal{L}ie_n$$

- (i) To find the  $G$ -orbits.
- (ii) To find the Zariski closure of every  $G$ -orbit.

## Definition

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{L}ie_n$ . We say that  $\mathfrak{g}$  degenerates to  $\mathfrak{h}$  ( $\mathfrak{g} \rightarrow \mathfrak{h}$ ) if

$$\mathfrak{h} \in \overline{G \cdot \mathfrak{g}}$$

# Example: Lie Algebras Case with $\mathbb{F} = \mathbb{R}$ or $\mathbb{F} = \mathbb{C}$

Consider the action "change of basis"

$$GL(\mathbb{F}^n) \times \mathcal{L}ie_n \rightarrow \mathcal{L}ie_n$$

- ▶ For  $n = 1$  there exist only one orbit:  
 $\mathbb{F}e$  with  $[e, e] = 0$ .
- ▶ For  $n = 2$ , there exist two orbits:  
 $\mathbb{F}e_1 + \mathbb{F}e_2$  with:
  - $\mathfrak{a}_0: [e_1, e_2] = 0$ .
  - $\mathfrak{a}_1: [e_1, e_2] = e_1$ .

$$\mathfrak{a}_1 \rightarrow \mathfrak{a}_0.$$

# Example: Lie Algebras Case with $\mathbb{F} = \mathbb{R}$ or $\mathbb{F} = \mathbb{C}$

Consider the action "change of basis"

$$GL(\mathbb{F}^n) \times \mathcal{L}ie_n \rightarrow \mathcal{L}ie_n$$

- ▶ For  $n = 1$  there exist only one orbit:  
 $\mathbb{F}e$  with  $[e, e] = 0$ .
- ▶ For  $n = 2$ , there exist two orbits:  
 $\mathbb{F}e_1 + \mathbb{F}e_2$  with:
  - $\mathfrak{a}_0: [e_1, e_2] = 0$ .
  - $\mathfrak{a}_1: [e_1, e_2] = e_1$ .

$$\mathfrak{a}_1 \rightarrow \mathfrak{a}_0.$$

# Example: Lie Algebras Case with $\mathbb{F} = \mathbb{R}$ or $\mathbb{F} = \mathbb{C}$

Consider the action "change of basis"

$$GL(\mathbb{F}^n) \times \mathcal{L}ie_n \rightarrow \mathcal{L}ie_n$$

- ▶ For  $n = 1$  there exist only one orbit:  
 $\mathbb{F}e$  with  $[e, e] = 0$ .

- ▶ For  $n = 2$ , there exist two orbits:  
 $\mathbb{F}e_1 + \mathbb{F}e_2$  with:

$$\mathfrak{a}_0: [e_1, e_2] = 0.$$

$$\mathfrak{a}_1: [e_1, e_2] = e_1.$$

$$\mathfrak{a}_1 \rightarrow \mathfrak{a}_0.$$

# Example: Lie Algebras Case with $\mathbb{F} = \mathbb{R}$ or $\mathbb{F} = \mathbb{C}$

Consider the action "change of basis"

$$GL(\mathbb{F}^n) \times \mathcal{L}ie_n \rightarrow \mathcal{L}ie_n$$

- ▶ For  $n = 1$  there exist only one orbit:  
 $\mathbb{F}e$  with  $[e, e] = 0$ .
  
- ▶ For  $n = 2$ , there exist two orbits:  
 $\mathbb{F}e_1 + \mathbb{F}e_2$  with:
  - $\mathfrak{a}_0: [e_1, e_2] = 0$ .
  - $\mathfrak{a}_1: [e_1, e_2] = e_1$ .

$$\mathfrak{a}_1 \rightarrow \mathfrak{a}_0.$$

# Example: Lie Algebras Case with $\mathbb{F} = \mathbb{R}$ or $\mathbb{F} = \mathbb{C}$

Consider the action "change of basis"

$$GL(\mathbb{F}^n) \times \mathcal{L}ie_n \rightarrow \mathcal{L}ie_n$$

- ▶ For  $n = 1$  there exist only one orbit:  
 $\mathbb{F}e$  with  $[e, e] = 0$ .
  
- ▶ For  $n = 2$ , there exist two orbits:  
 $\mathbb{F}e_1 + \mathbb{F}e_2$  with:
  - $\mathfrak{a}_0: [e_1, e_2] = 0$ .
  - $\mathfrak{a}_1: [e_1, e_2] = e_1$ .

$$\mathfrak{a}_1 \rightarrow \mathfrak{a}_0.$$

# Example: Lie Algebras Case with $\mathbb{F} = \mathbb{R}$ or $\mathbb{F} = \mathbb{C}$

Consider the action "change of basis"

$$GL(V) \times \mathcal{L}ie_n \rightarrow \mathcal{L}ie_n$$

- ▶ For  $n = 3$  there exist an infinite number of orbits:  
 $\mathbb{F}e_1 + \mathbb{F}e_2 + \mathbb{F}e_3$  with:

	$\mathfrak{sl}_2$	$\mathfrak{su}_2$	$\mathfrak{r}$	$\mathfrak{q}(\beta)$	$\mathfrak{p}(\alpha)$	$\mathfrak{h}$	$\mathfrak{a}$
$[e_2, e_3]$	$e_1$	$e_1$	$-(e_1 + e_3)$	$e_1 - \beta e_3$	$\alpha e_3$	0	0
$[e_3, e_1]$	$e_2$	$e_2$	0	0	0	0	0
$[e_1, e_2]$	$e_3$	$-e_3$	$e_1$	$\beta e_1 + e_3$	$e_1$	$e_3$	0

with  $\alpha, \beta \in \mathbb{R}$ . Over  $\mathbb{C}$ :  $\mathfrak{sl}_2 \simeq \mathfrak{su}_2$  and  $\mathfrak{r} \simeq \mathfrak{q}(\beta)$ .

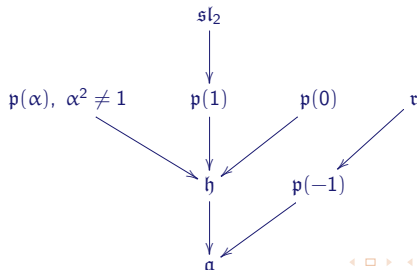


# Example: Lie Algebras with $\mathbb{F} = \mathbb{C}$

[D. Burde and C. Steinhoff, 1998]

For  $n = 3$ .

	$\mathfrak{sl}_2$	$\mathfrak{r}$	$\mathfrak{p}(\alpha)$	$\mathfrak{h}$	$\mathfrak{a}$
$[e_2, e_3]$	$e_1$	$-(e_1 + e_3)$	$\alpha e_3$	0	0
$[e_3, e_1]$	$e_2$	0	0	0	0
$[e_1, e_2]$	$e_3$	$e_1$	$e_1$	$e_3$	0



# The Lie superalgebra case

# Supervector spaces

**Super** =  $\mathbb{Z}_2$ -graded.

## Definition

A supervector space is a vector space  $V = V_0 \oplus V_1$ .

- ▶ The subspaces  $V_0$  and  $V_1$  are called the even and the odd parts of  $V$ , resp.
- ▶ The elements in  $(V_0 \cup V_1) \setminus \{0\}$  are called homogeneous.
- ▶ The degree of a homogeneous element is defined as

$$|x| = i, \quad \text{if } x \in V_i \setminus \{0\}.$$

- ▶ If  $\dim(V_0) = m$  and  $\dim(V_1) = n$  we say that

$$\dim(V) = (m, n).$$

# Supervector spaces

**Super** =  $\mathbb{Z}_2$ -graded.

## Definition

A supervector space is a vector space  $V = V_0 \oplus V_1$ .

- ▶ The subspaces  $V_0$  and  $V_1$  are called the even and the odd parts of  $V$ , resp.
- ▶ The elements in  $(V_0 \cup V_1) \setminus \{0\}$  are called homogeneous.
- ▶ The degree of a homogeneous element is defined as

$$|x| = i, \quad \text{if } x \in V_i \setminus \{0\}.$$

- ▶ If  $\dim(V_0) = m$  and  $\dim(V_1) = n$  we say that

$$\dim(V) = (m, n).$$

# Supervector spaces

**Super** =  $\mathbb{Z}_2$ -graded.

## Definition

A supervector space is a vector space  $V = V_0 \oplus V_1$ .

- ▶ The subspaces  $V_0$  and  $V_1$  are called the even and the odd parts of  $V$ , resp.
- ▶ The elements in  $(V_0 \cup V_1) \setminus \{0\}$  are called homogeneous.
- ▶ The degree of a homogeneous element is defined as

$$|x| = i, \quad \text{if } x \in V_i \setminus \{0\}.$$

- ▶ If  $\dim(V_0) = m$  and  $\dim(V_1) = n$  we say that

$$\dim(V) = (m, n).$$

# Supervector spaces

**Super** =  $\mathbb{Z}_2$ -graded.

## Definition

A supervector space is a vector space  $V = V_0 \oplus V_1$ .

- ▶ The subspaces  $V_0$  and  $V_1$  are called the even and the odd parts of  $V$ , resp.
- ▶ The elements in  $(V_0 \cup V_1) \setminus \{0\}$  are called homogeneous.
- ▶ The degree of a homogeneous element is defined as

$$|x| = i, \quad \text{if } x \in V_i \setminus \{0\}.$$

- ▶ If  $\dim(V_0) = m$  and  $\dim(V_1) = n$  we say that

$$\dim(V) = (m, n).$$

# Supervector spaces

**Super** =  $\mathbb{Z}_2$ -graded.

## Definition

A supervector space is a vector space  $V = V_0 \oplus V_1$ .

- ▶ The subspaces  $V_0$  and  $V_1$  are called the even and the odd parts of  $V$ , resp.
- ▶ The elements in  $(V_0 \cup V_1) \setminus \{0\}$  are called homogeneous.
- ▶ The degree of a homogeneous element is defined as

$$|x| = i, \quad \text{if } x \in V_i \setminus \{0\}.$$

- ▶ If  $\dim(V_0) = m$  and  $\dim(V_1) = n$  we say that

$$\dim(V) = (m, n).$$

# Supervector spaces

**Super** =  $\mathbb{Z}_2$ -graded.

## Definition

A supervector space is a vector space  $V = V_0 \oplus V_1$ .

- ▶ The subspaces  $V_0$  and  $V_1$  are called the even and the odd parts of  $V$ , resp.
- ▶ The elements in  $(V_0 \cup V_1) \setminus \{0\}$  are called homogeneous.
- ▶ The degree of a homogeneous element is defined as

$$|x| = i, \quad \text{if } x \in V_i \setminus \{0\}.$$

- ▶ If  $\dim(V_0) = m$  and  $\dim(V_1) = n$  we say that

$$\dim(V) = (m, n).$$



# Superalgebras

## Definition

A superalgebra  $\mathcal{A} = \mathcal{A}_0 \oplus \mathcal{A}_1$  is a supervector space with a bilinear map  $\mathcal{A} \times \mathcal{A} \rightarrow \mathcal{A}$  such that

$$\mathcal{A}_i \mathcal{A}_j \subset \mathcal{A}_{i+j}, \quad i, j \in \mathbb{Z}_2.$$

## Remark

- (i)  $\mathcal{A}_0$  is a subalgebra.
- (ii)  $\mathcal{A}_1$  is an  $\mathcal{A}_0$ -module.

# Superalgebras

## Definition

A superalgebra  $\mathcal{A} = \mathcal{A}_0 \oplus \mathcal{A}_1$  is a supervector space with a bilinear map  $\mathcal{A} \times \mathcal{A} \rightarrow \mathcal{A}$  such that

$$\mathcal{A}_i \mathcal{A}_j \subset \mathcal{A}_{i+j}, \quad i, j \in \mathbb{Z}_2.$$

## Remark

- (i)  $\mathcal{A}_0$  is a subalgebra.
- (ii)  $\mathcal{A}_1$  is an  $\mathcal{A}_0$ -module.

# Superalgebras

## Definition

A superalgebra  $\mathcal{A} = \mathcal{A}_0 \oplus \mathcal{A}_1$  is a supervector space with a bilinear map  $\mathcal{A} \times \mathcal{A} \rightarrow \mathcal{A}$  such that

$$\mathcal{A}_i \mathcal{A}_j \subset \mathcal{A}_{i+j}, \quad i, j \in \mathbb{Z}_2.$$

## Remark

- (i)  $\mathcal{A}_0$  is a subalgebra.
- (ii)  $\mathcal{A}_1$  is an  $\mathcal{A}_0$ -module.

# Superalgebras

## Definition

A superalgebra  $\mathcal{A} = \mathcal{A}_0 \oplus \mathcal{A}_1$  is a supervector space with a bilinear map  $\mathcal{A} \times \mathcal{A} \rightarrow \mathcal{A}$  such that

$$\mathcal{A}_i \mathcal{A}_j \subset \mathcal{A}_{i+j}, \quad i, j \in \mathbb{Z}_2.$$

## Remark

- (i)  $\mathcal{A}_0$  is a subalgebra.
- (ii)  $\mathcal{A}_1$  is an  $\mathcal{A}_0$ -module.

# Superalgebras

## Example

Let  $V = V_0 \oplus V_1$  be a supervector space. Let  $T : V \rightarrow V$ ,

$$\text{End}(V_0|V_1)_0 \ni T \iff T = X \oplus Y \iff \begin{pmatrix} X & 0 \\ 0 & Y \end{pmatrix}, \quad \text{where} \quad \begin{array}{l} X : V_0 \rightarrow V_0 \\ Y : V_1 \rightarrow V_1 \end{array}$$

$$\text{End}(V_0|V_1)_1 \ni T \iff T = Z \oplus W \iff \begin{pmatrix} 0 & W \\ Z & 0 \end{pmatrix}, \quad \text{where} \quad \begin{array}{l} Z : V_0 \rightarrow V_1 \\ W : V_1 \rightarrow V_0 \end{array}$$

Then,

$$\text{End}(V) = \text{End}(V_0|V_1)_0 \oplus \text{End}(V_0|V_1)_1$$

# Superalgebras

## Example

Let  $V = V_0 \oplus V_1$  be a supervector space. Let  $T : V \rightarrow V$ ,

$$\text{End}(V_0|V_1)_0 \ni T \iff T = X \oplus Y \leftrightarrow \begin{pmatrix} X & 0 \\ 0 & Y \end{pmatrix}, \quad \text{where} \quad \begin{array}{l} X : V_0 \rightarrow V_0 \\ Y : V_1 \rightarrow V_1 \end{array}$$

$$\text{End}(V_0|V_1)_1 \ni T \iff T = Z \oplus W \leftrightarrow \begin{pmatrix} 0 & W \\ Z & 0 \end{pmatrix}, \quad \text{where} \quad \begin{array}{l} Z : V_0 \rightarrow V_1 \\ W : V_1 \rightarrow V_0 \end{array}$$

Then,

$$\text{End}(V) = \text{End}(V_0|V_1)_0 \oplus \text{End}(V_0|V_1)_1$$

# Superalgebras

## Example

Let  $V = V_0 \oplus V_1$  be a supervector space. Let  $T : V \rightarrow V$ ,

$$\text{End}(V_0|V_1)_0 \ni T \iff T = X \oplus Y \leftrightarrow \begin{pmatrix} X & 0 \\ 0 & Y \end{pmatrix}, \quad \text{where} \quad \begin{array}{l} X : V_0 \rightarrow V_0 \\ Y : V_1 \rightarrow V_1 \end{array}$$

$$\text{End}(V_0|V_1)_1 \ni T \iff T = Z \oplus W \leftrightarrow \begin{pmatrix} 0 & W \\ Z & 0 \end{pmatrix}, \quad \text{where} \quad \begin{array}{l} Z : V_0 \rightarrow V_1 \\ W : V_1 \rightarrow V_0 \end{array}$$

Then,

$$\text{End}(V) = \text{End}(V_0|V_1)_0 \oplus \text{End}(V_0|V_1)_1$$

# Superalgebras

## Example

Let  $V = V_0 \oplus V_1$  be a supervector space. Let  $T : V \rightarrow V$ ,

$$\text{End}(V_0|V_1)_0 \ni T \iff T = X \oplus Y \leftrightarrow \begin{pmatrix} X & 0 \\ 0 & Y \end{pmatrix}, \quad \text{where} \quad \begin{array}{l} X : V_0 \rightarrow V_0 \\ Y : V_1 \rightarrow V_1 \end{array}$$

$$\text{End}(V_0|V_1)_1 \ni T \iff T = Z \oplus W \leftrightarrow \begin{pmatrix} 0 & W \\ Z & 0 \end{pmatrix}, \quad \text{where} \quad \begin{array}{l} Z : V_0 \rightarrow V_1 \\ W : V_1 \rightarrow V_0 \end{array}$$

Then,

$$\text{End}(V) = \text{End}(V_0|V_1)_0 \oplus \text{End}(V_0|V_1)_1$$



# Superalgebras

## Example

Let  $V = V_0 \oplus V_1$  be a supervector space. Define

$$\text{End}(V_0|V_1)_0 \ni T \iff T = \begin{pmatrix} X & 0 \\ 0 & Y \end{pmatrix}, \quad \text{where } \begin{array}{l} X: V_0 \rightarrow V_0 \\ Y: V_1 \rightarrow V_1 \end{array}$$

$$\text{End}(V_0|V_1)_1 \ni T \iff T = \begin{pmatrix} 0 & W \\ Z & 0 \end{pmatrix}, \quad \text{where } \begin{array}{l} Z: V_0 \rightarrow V_1 \\ W: V_1 \rightarrow V_0 \end{array}$$

Then

$$\text{End}(V_0|V_1) := \text{End}(V) = \text{End}(V_0|V_1)_0 \oplus \text{End}(V_0|V_1)_1,$$

and  $\text{End}(V_0|V_1)$  is a superalgebra with the composition of functions as product.

# Superalgebras

## Example

Let  $V = V_0 \oplus V_1$  be a supervector space. Define

$$\text{End}(V_0|V_1)_0 \ni T \iff T = \begin{pmatrix} X & 0 \\ 0 & Y \end{pmatrix}, \quad \text{where } \begin{array}{l} X: V_0 \rightarrow V_0 \\ Y: V_1 \rightarrow V_1 \end{array}$$

$$\text{End}(V_0|V_1)_1 \ni T \iff T = \begin{pmatrix} 0 & W \\ Z & 0 \end{pmatrix}, \quad \text{where } \begin{array}{l} Z: V_0 \rightarrow V_1 \\ W: V_1 \rightarrow V_0 \end{array}$$

Then

$$\text{End}(V_0|V_1) := \text{End}(V) = \text{End}(V_0|V_1)_0 \oplus \text{End}(V_0|V_1)_1,$$

and  $\text{End}(V_0|V_1)$  is a superalgebra with the composition of functions as product.

# Lie Superalgebras

## Definition

A Lie superalgebra is a superalgebra  $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$  with product  $[[\cdot, \cdot]] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , where the homogeneous elements satisfy:

(i) The super skew-symmetry

$$[[x, y]] = -(-1)^{|x||y|} [[y, x]].$$

(ii) The super Jacobi identity

$$(-1)^{|x||z|} [[x, y], z] + (-1)^{|x||y|} [[y, z], x] + (-1)^{|y||z|} [[z, x], y] = 0,$$

Notice that  $\mathfrak{g}_0$  is a Lie algebra, and  $\mathfrak{g}_1$  is  $\mathfrak{g}_0$ -module.

# Lie Superalgebras

## Definition

A Lie superalgebra is a superalgebra  $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$  with product  $[[\cdot, \cdot]] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , where the homogeneous elements satisfy:

(i) The super skew-symmetry

$$[[x, y]] = -(-1)^{|x||y|} [[y, x]].$$

(ii) The super Jacobi identity

$$(-1)^{|x||z|} [[x, y], z] + (-1)^{|x||y|} [[y, z], x] + (-1)^{|y||z|} [[z, x], y] = 0,$$

Notice that  $\mathfrak{g}_0$  is a Lie algebra, and  $\mathfrak{g}_1$  is  $\mathfrak{g}_0$ -module.

# Lie Superalgebras

## Definition

A Lie superalgebra is a superalgebra  $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$  with product  $[[\cdot, \cdot]] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , where the homogeneous elements satisfy:

(i) The super skew-symmetry

$$[[x, y]] = -(-1)^{|x||y|} [[y, x]].$$

(ii) The super Jacobi identity

$$(-1)^{|x||z|} [[x, y], z] + (-1)^{|x||y|} [[y, z], x] + (-1)^{|y||z|} [[z, x], y] = 0,$$

Notice that  $\mathfrak{g}_0$  is a Lie algebra, and  $\mathfrak{g}_1$  is  $\mathfrak{g}_0$ -module.

# Lie Superalgebras

## Example

Let  $V = V_0 \oplus V_1$  be a supervector space, and let  $T, S \in \text{End}(V_0|V_1)$  homogeneous. Define:

$$[[T, S]] = T \circ S - (-1)^{|T||S|} S \circ T.$$

Then,  $\mathfrak{gl}(V_0|V_1) := (\text{End}(V_0|V_1), [[\cdot, \cdot]])$  is a Lie superalgebra.

## Definition

Let  $T \in \text{End}(V_0|V_1)$ . Define the supertrace as follows

$$\text{if } T = \begin{pmatrix} X & Y \\ Z & W \end{pmatrix}, \text{ then } \text{str}(T) = \text{tr}(X) - \text{tr}(W).$$

## Example

The superalgebra  $\mathfrak{sl}(V_0|V_1) = \{T \in \text{End}(V_0|V_1) | \text{str}(T) = 0\} \subset \mathfrak{gl}(V_0|V_1)$

# Lie Superalgebras

## Example

Let  $V = V_0 \oplus V_1$  be a supervector space, and let  $T, S \in \text{End}(V_0|V_1)$  homogeneous. Define:

$$[[T, S]] = T \circ S - (-1)^{|T||S|} S \circ T.$$

Then,  $\mathfrak{gl}(V_0|V_1) := (\text{End}(V_0|V_1), [[\cdot, \cdot]])$  is a Lie superalgebra.

## Definition

Let  $T \in \text{End}(V_0|V_1)$ . Define the supertrace as follows

$$\text{if } T = \begin{pmatrix} X & Y \\ Z & W \end{pmatrix}, \quad \text{then } \text{str}(T) = \text{tr}(X) - \text{tr}(W).$$

## Example

The superalgebra  $\mathfrak{sl}(V_0|V_1) = \{T \in \text{End}(V_0|V_1) | \text{str}(T) = 0\} \subset \mathfrak{gl}(V_0|V_1)$

# Lie Superalgebras

## Example

Let  $V = V_0 \oplus V_1$  be a supervector space, and let  $T, S \in \text{End}(V_0|V_1)$  homogeneous. Define:

$$[[T, S]] = T \circ S - (-1)^{|T||S|} S \circ T.$$

Then,  $\mathfrak{gl}(V_0|V_1) := (\text{End}(V_0|V_1), [[\cdot, \cdot]])$  is a Lie superalgebra.

## Definition

Let  $T \in \text{End}(V_0|V_1)$ . Define the supertrace as follows

$$\text{if } T = \begin{pmatrix} X & Y \\ Z & W \end{pmatrix}, \quad \text{then } \text{str}(T) = \text{tr}(X) - \text{tr}(W).$$

## Example

The superalgebra  $\mathfrak{sl}(V_0|V_1) = \{T \in \text{End}(V_0|V_1) | \text{str}(T) = 0\} \subset \mathfrak{gl}(V_0|V_1)$



# Lie Superalgebras

## Example

Let  $V = V_0 \oplus V_1$  be a supervector space, and let  $T, S \in \text{End}(V_0|V_1)$  homogeneous. Define:

$$[[T, S]] = T \circ S - (-1)^{|T||S|} S \circ T.$$

Then,  $\mathfrak{gl}(V_0|V_1) := (\text{End}(V_0|V_1), [[\cdot, \cdot]])$  is a Lie superalgebra.

## Definition

Let  $T \in \text{End}(V_0|V_1)$ . Define the supertrace as follows

$$\text{if } T = \begin{pmatrix} X & Y \\ Z & W \end{pmatrix}, \quad \text{then } \text{str}(T) = \text{tr}(X) - \text{tr}(W).$$

## Example

The superalgebra  $\mathfrak{sl}(V_0|V_1) = \{T \in \text{End}(V_0|V_1) | \text{str}(T) = 0\} \subset \mathfrak{gl}(V_0|V_1)$

# Morphisms

## Definition

Let  $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$  and  $\mathfrak{g}' = \mathfrak{g}'_0 \oplus \mathfrak{g}'_1$  be Lie superalgebras. A Lie superalgebra morphism  $\Phi : \mathfrak{g} \rightarrow \mathfrak{g}'$  is a linear map such that

$$\Phi([\cdot, \cdot]_{\mathfrak{g}}) = [[\Phi(\cdot), \Phi(\cdot)]_{\mathfrak{g}'}]$$

## Remark

- ▶ Notice that  $\Phi$  is an even map, i.e.,

$$\Phi(\mathfrak{g}_0) \subset \mathfrak{g}'_0 \quad \text{and} \quad \Phi(\mathfrak{g}_1) \subset \mathfrak{g}'_1.$$

- ▶ We can write  $\Phi = T \oplus S$ , where  $T : \mathfrak{g}_0 \rightarrow \mathfrak{g}'_0$  is a Lie algebra morphism, and  $S : \mathfrak{g}_1 \rightarrow \mathfrak{g}'_1$  is a  $\mathfrak{g}_0$ -module morphism such that

$$S([\cdot, \cdot]_{\mathfrak{g}}) = [[T(\cdot), S(\cdot)]_{\mathfrak{g}'_0}],$$

$$T([\cdot, \cdot]_{\mathfrak{g}}) = [[S(\cdot), S(\cdot)]_{\mathfrak{g}'_1}].$$

# Morphisms

## Definition

Let  $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$  and  $\mathfrak{g}' = \mathfrak{g}'_0 \oplus \mathfrak{g}'_1$  be Lie superalgebras. A Lie superalgebra morphism  $\Phi : \mathfrak{g} \rightarrow \mathfrak{g}'$  is a linear map such that

$$\Phi([\cdot, \cdot]_{\mathfrak{g}}) = [[\Phi(\cdot), \Phi(\cdot)]_{\mathfrak{g}'}]$$

## Remark

- ▶ Notice that  $\Phi$  is an even map, i.e.,

$$\Phi(\mathfrak{g}_0) \subset \mathfrak{g}'_0 \quad \text{and} \quad \Phi(\mathfrak{g}_1) \subset \mathfrak{g}'_1.$$

- ▶ We can write  $\Phi = T \oplus S$ , where  $T : \mathfrak{g}_0 \rightarrow \mathfrak{g}'_0$  is a Lie algebra morphism, and  $S : \mathfrak{g}_1 \rightarrow \mathfrak{g}'_1$  is a  $\mathfrak{g}_0$ -module morphism such that

$$S([\cdot, \cdot]_{\mathfrak{g}}) = [[T(\cdot), S(\cdot)]_{\mathfrak{g}'_0}],$$

$$T([\cdot, \cdot]_{\mathfrak{g}}) = [[S(\cdot), S(\cdot)]_{\mathfrak{g}'_1}].$$

# Morphisms

## Definition

Let  $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$  and  $\mathfrak{g}' = \mathfrak{g}'_0 \oplus \mathfrak{g}'_1$  be Lie superalgebras. A Lie superalgebra morphism  $\Phi : \mathfrak{g} \rightarrow \mathfrak{g}'$  is a linear map such that

$$\Phi([\cdot, \cdot]_{\mathfrak{g}}) = [[\Phi(\cdot), \Phi(\cdot)]_{\mathfrak{g}'}]$$

## Remark

- ▶ Notice that  $\Phi$  is an even map, i.e.,

$$\Phi(\mathfrak{g}_0) \subset \mathfrak{g}'_0 \quad \text{and} \quad \Phi(\mathfrak{g}_1) \subset \mathfrak{g}'_1.$$

- ▶ We can write  $\Phi = T \oplus S$ , where  $T : \mathfrak{g}_0 \rightarrow \mathfrak{g}'_0$  is a Lie algebra morphism, and  $S : \mathfrak{g}_1 \rightarrow \mathfrak{g}'_1$  is a  $\mathfrak{g}_0$ -module morphism such that

$$S([\cdot, \cdot]) = [[T(\cdot), S(\cdot)]],$$

$$T([\cdot, \cdot]) = [[S(\cdot), S(\cdot)]].$$

# The Variety $\mathcal{LS}^{(m,n)}$

Let  $V = V_0 \oplus V_1$  be a complex  $(m, n)$ -dimensional supervector space with a fixed homogeneous basis  $\{e_1, \dots, e_m, f_1, \dots, f_n\}$ . Given a Lie superalgebra structure on  $V$ , we identify  $\mathfrak{g} = (V, [\cdot, \cdot])$  with its set of structure constants

$$\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1 \longleftrightarrow (c_{ij}^k, \rho_{ij}^k, \Gamma_{ij}^k) \in \mathbb{C}^{m^3+2mn^2}$$

where

$$[[e_i, e_j]] = \sum_{k=1}^m c_{ij}^k e_k, \quad [[e_i, f_j]] = \sum_{k=1}^n \rho_{ij}^k f_k, \quad \text{and} \quad [[f_i, f_j]] = \sum_{k=1}^m \Gamma_{ij}^k e_k.$$

## Notation

$\mathcal{LS}^{(m,n)}$  denotes the Lie superalgebra variety of dimension  $(m, n)$  over  $\mathbb{C}$ .

# The Variety $\mathcal{LS}^{(m,n)}$

Let  $V = V_0 \oplus V_1$  be a complex  $(m, n)$ -dimensional supervector space with a fixed homogeneous basis  $\{e_1, \dots, e_m, f_1, \dots, f_n\}$ . Given a Lie superalgebra structure on  $V$ , we identify  $\mathfrak{g} = (V, \llbracket \cdot, \cdot \rrbracket)$  with its set of structure constants

$$\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1 \longleftrightarrow (c_{ij}^k, \rho_{ij}^k, \Gamma_{ij}^k) \in \mathbb{C}^{m^3+2mn^2}$$

where

$$\llbracket e_i, e_j \rrbracket = \sum_{k=1}^m c_{ij}^k e_k, \quad \llbracket e_i, f_j \rrbracket = \sum_{k=1}^n \rho_{ij}^k f_k, \quad \text{and} \quad \llbracket f_i, f_j \rrbracket = \sum_{k=1}^m \Gamma_{ij}^k e_k.$$

## Notation

$\mathcal{LS}^{(m,n)}$  denotes the Lie superalgebra variety of dimension  $(m, n)$  over  $\mathbb{C}$ .

# The Action by “Change of Basis”

Let  $G = \mathrm{GL}_m(\mathbb{C}) \oplus \mathrm{GL}_n(\mathbb{C})$ . We have the action  $G \times \mathcal{LS}^{(m,n)} \rightarrow \mathcal{LS}^{(m,n)}$  given by

$$g \cdot [\cdot, \cdot] = g[[g^{-1}(\cdot), g^{-1}(\cdot)]]$$

# An Amazing Dream

To find:

- ▶ the  $G$ -orbits,
- ▶ the Zariski closure of every  $G$ -orbit,

for

$$\mathcal{LS}(m, n), \quad m, n \in \mathbb{N}.$$

## The reality

We studied the problem for

$$\mathcal{LS}(2, 2).$$



# An Amazing Dream

To find:

- ▶ the  $G$ -orbits,
- ▶ the Zariski closure of every  $G$ -orbit,

for

$$\mathcal{LS}^{(m,n)}, \quad m, n \in \mathbb{N}.$$

The reality

We studied the problem for

$$\mathcal{LS}^{(2,2)}.$$

# An Amazing Dream

To find:

- ▶ the  $G$ -orbits,
- ▶ the Zariski closure of every  $G$ -orbit,

for

$$\mathcal{LS}^{(m,n)}, \quad m, n \in \mathbb{N}.$$

## The reality

We studied the problem for

$$\mathcal{LS}^{(2,2)}.$$

The  $G$ -orbits of  $\mathcal{LS}^{(2,2)}$ 

## Theorem (Alvarez, M.A., -)

Let  $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$  be a complex Lie superalgebra of dimension  $(2, 2)$ , then  $\mathfrak{g}$  is isomorphic to one and only one of the following:

$$\begin{aligned}
 \mathcal{LS}_0 : & \quad [[\cdot, \cdot]] = 0. \\
 \mathcal{LS}_1 : & \quad [[f_1, f_1]] = e_1, \quad [[f_2, f_2]] = e_2. \\
 \mathcal{LS}_2 : & \quad [[f_1, f_1]] = e_1, \quad [[f_2, f_2]] = e_1. \\
 \mathcal{LS}_3 : & \quad [[f_1, f_1]] = e_1. \\
 \mathcal{LS}_4 : & \quad [[f_1, f_2]] = e_1, \quad [[f_2, f_2]] = e_2. \\
 \mathcal{LS}_5 : & \quad [[e_1, f_1]] = f_1, \quad [[e_2, f_2]] = f_2. \\
 \mathcal{LS}_6(\alpha) : & \quad [[e_2, f_1]] = f_1, \quad [[e_2, f_2]] = \alpha f_2. \\
 \mathcal{LS}_7 : & \quad [[e_2, f_1]] = f_1, \quad [[e_2, f_2]] = -f_2, \quad [[f_1, f_2]] = e_1. \\
 \mathcal{LS}_8 : & \quad [[e_2, f_1]] = f_1, \quad [[f_2, f_2]] = e_1. \\
 \mathcal{LS}_9 : & \quad [[e_1, f_1]] = f_1, \quad [[e_1, f_2]] = f_2, \quad [[e_2, f_2]] = f_1. \\
 \mathcal{LS}_{10} : & \quad [[e_2, f_1]] = f_1, \quad [[e_2, f_2]] = f_1 + f_2. \\
 \mathcal{LS}_{11} : & \quad [[e_2, f_2]] = f_1. \\
 \mathcal{LS}_{12} : & \quad [[e_2, f_2]] = f_1, \quad [[f_2, f_2]] = e_1.
 \end{aligned}$$

The G-orbits of  $\mathcal{LS}^{(2,2)}$ 

$$\begin{array}{lll}
\mathcal{LS}_{13}(\alpha, \beta) : & \llbracket e_1, e_2 \rrbracket = e_1, & \llbracket e_2, f_1 \rrbracket = \alpha f_1, \quad \llbracket e_2, f_2 \rrbracket = \beta f_2. \\
\mathcal{LS}_{14}(\alpha) : & \llbracket e_1, e_2 \rrbracket = e_1, & \llbracket e_2, f_1 \rrbracket = \alpha f_1, \quad \llbracket e_2, f_2 \rrbracket = -(\alpha + 1)f_2, \\
& \llbracket f_1, f_2 \rrbracket = e_1, & \alpha \neq -\frac{1}{2}. \\
\mathcal{LS}_{15}(\alpha) : & \llbracket e_1, e_2 \rrbracket = e_1, & \llbracket e_2, f_1 \rrbracket = \alpha f_1, \quad \llbracket e_2, f_2 \rrbracket = -\frac{1}{2}f_2, \\
& \llbracket f_1, f_1 \rrbracket = \delta_{-\frac{1}{2}, \alpha} e_1, & \llbracket f_2, f_2 \rrbracket = e_1. \\
\mathcal{LS}_{16} : & \llbracket e_1, e_2 \rrbracket = e_1, & \llbracket e_2, f_1 \rrbracket = -\frac{1}{2}f_1, \quad \llbracket e_2, f_2 \rrbracket = -\frac{1}{2}f_2, \\
& \llbracket f_1, f_1 \rrbracket = e_1. \\
\mathcal{LS}_{17}(\alpha) : & \llbracket e_1, e_2 \rrbracket = e_1, & \llbracket e_2, f_1 \rrbracket = \alpha f_1, \quad \llbracket e_2, f_2 \rrbracket = f_1 + \alpha f_2, \\
& \llbracket f_2, f_2 \rrbracket = \delta_{-\frac{1}{2}, \alpha} e_1. \\
\mathcal{LS}_{18} : & \llbracket e_1, e_2 \rrbracket = e_1, & \llbracket e_2, f_1 \rrbracket = -\frac{1}{2}f_1, \quad \llbracket e_2, f_2 \rrbracket = f_1 - \frac{1}{2}f_2. \\
\mathcal{LS}_{19}(\alpha) : & \llbracket e_1, e_2 \rrbracket = e_1, & \llbracket e_1, f_2 \rrbracket = f_1, \quad \llbracket e_2, f_1 \rrbracket = \alpha f_1, \\
& \llbracket e_2, f_2 \rrbracket = (\alpha + 1)f_2, & \llbracket f_1, f_2 \rrbracket = \delta_{-1, \alpha} e_1, \quad \llbracket f_2, f_2 \rrbracket = 2\delta_{-1, \alpha} e_2. \\
\mathcal{LS}_{20} : & \llbracket e_1, e_2 \rrbracket = e_1, & \llbracket e_1, f_2 \rrbracket = f_1, \quad \llbracket e_2, f_1 \rrbracket = -f_1,
\end{array}$$

where  $\alpha, \beta \in \mathbb{C}$ .

- ▶  $\mathcal{LS}_n(\alpha) \simeq \mathcal{LS}_n(\alpha') \Leftrightarrow \alpha = \alpha'$ , for  $n \in \{6, 15, 17, 19\}$
- ▶  $\mathcal{LS}_{14}(\alpha) \simeq \mathcal{LS}_{14}(\alpha') \Leftrightarrow$  either  $\alpha = \alpha'$  or  $\alpha + \alpha' = -1$ .
- ▶  $\mathcal{LS}_{13}(\alpha, \beta) \simeq \mathcal{LS}_{13}(\alpha', \beta') \Leftrightarrow \{\alpha, \beta\} = \{\alpha', \beta'\}$ .

## Next Step

To find the orbit closure for each Lie superalgebra  $\mathcal{LS}_n$ ,  
for  $n = 0, \dots, 20$ .

# Degenerations in $\mathcal{LS}^{(m,n)}$

## Definition

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$ . We say that  $\mathfrak{g}$  degenerates to  $\mathfrak{h}$  (denoted by  $\mathfrak{g} \rightarrow \mathfrak{h}$ ) if

$$\mathfrak{h} \in \overline{G \cdot \mathfrak{g}} \quad (\text{Zariski closure})$$

## Remark

Notice that

$$\text{if } \mathfrak{g} \rightarrow \mathfrak{h} \text{ and } \mathfrak{h} \rightarrow \mathfrak{s}, \text{ then } \mathfrak{g} \rightarrow \mathfrak{s}.$$

# Degenerations in $\mathcal{LS}^{(m,n)}$

## Definition

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$ . We say that  $\mathfrak{g}$  degenerates to  $\mathfrak{h}$  (denoted by  $\mathfrak{g} \rightarrow \mathfrak{h}$ ) if

$$\mathfrak{h} \in \overline{G \cdot \mathfrak{g}} \quad (\text{Zariski closure})$$

## Remark

Notice that

$$\text{if } \mathfrak{g} \rightarrow \mathfrak{h} \text{ and } \mathfrak{h} \rightarrow \mathfrak{s}, \text{ then } \mathfrak{g} \rightarrow \mathfrak{s}.$$

# Degenerations in $\mathcal{LS}^{(m,n)}$

## Lemma

Let  $\mathbb{C}(t)$  be the field of fractions of the polynomial ring  $\mathbb{C}[t]$ , and let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$ . If there exists a continuous map

$$(0, 1] \rightarrow \mathrm{GL}_m(\mathbb{C}(t)) \oplus \mathrm{GL}_n(\mathbb{C}(t)), \quad t \mapsto g_t$$

such that  $\lim_{t \rightarrow 0} g_t \cdot \mathfrak{g} = \mathfrak{h}$ , then  $\mathfrak{g} \rightarrow \mathfrak{h}$ .

## Remark

Let  $\mathfrak{g} \in \mathcal{LS}^{(m,n)}$ , then  $\mathfrak{g}$  degenerates to the trivial Lie superalgebra  $\mathfrak{a} = (0, 0, 0)$  (take  $t \rightarrow t^{-1}(\mathrm{id}_m \oplus \mathrm{id}_n)$ ).



# Degenerations in $\mathcal{LS}^{(m,n)}$

## Lemma

Let  $\mathbb{C}(t)$  be the field of fractions of the polynomial ring  $\mathbb{C}[t]$ , and let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$ . If there exists a continuous map

$$(0, 1] \rightarrow \mathrm{GL}_m(\mathbb{C}(t)) \oplus \mathrm{GL}_n(\mathbb{C}(t)), \quad t \mapsto g_t$$

such that  $\lim_{t \rightarrow 0} g_t \cdot \mathfrak{g} = \mathfrak{h}$ , then  $\mathfrak{g} \rightarrow \mathfrak{h}$ .

## Remark

Let  $\mathfrak{g} \in \mathcal{LS}^{(m,n)}$ , then  $\mathfrak{g}$  degenerates to the trivial Lie superalgebra  $\mathfrak{a} = (0, 0, 0)$  (take  $t \rightarrow t^{-1}(\mathrm{id}_m \oplus \mathrm{id}_n)$ ).

# Degenerations in $\mathcal{LS}^{(m,n)}$

## Lemma

Let  $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$ ,  $\mathfrak{h} = \mathfrak{h}_0 \oplus \mathfrak{h}_1 \in \mathcal{LS}^{(m,n)}$ . If  $\mathfrak{g} \rightarrow \mathfrak{h}$ , then  $\mathfrak{g}_0 \rightarrow \mathfrak{h}_0$ .

# Degenerations in $\mathcal{LS}^{(m,n)}$

## Definition

Let  $\mathfrak{g} = \{c_{ij}^k, \rho_{ij}^k, \Gamma_{ij}^k\} \in \mathcal{LS}^{(m,n)}$ .

- (i) The **abelianization of  $\mathfrak{g}$**  is defined as  $\text{ab}(\mathfrak{g}) = \{0, 0, \Gamma_{ij}^k\}$ .
- (ii) The **forgetful Lie superalgebra of  $\mathfrak{g}$**  is defined as  $\mathcal{F}(\mathfrak{g}) = \{c_{ij}^k, \rho_{ij}^k, 0\}$ .

## Lemma

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$ . If  $\mathfrak{g} \rightarrow \mathfrak{h}$ , then

- (i)  $\text{ab}(\mathfrak{g}) \rightarrow \text{ab}(\mathfrak{h})$ .
- (ii)  $\mathcal{F}(\mathfrak{g}) \rightarrow \mathcal{F}(\mathfrak{h})$ .

# Degenerations in $\mathcal{LS}^{(m,n)}$

## Definition

Let  $\mathfrak{g} = \{c_{ij}^k, \rho_{ij}^k, \Gamma_{ij}^k\} \in \mathcal{LS}^{(m,n)}$ .

- (i) The **abelianization of  $\mathfrak{g}$**  is defined as  $\text{ab}(\mathfrak{g}) = \{0, 0, \Gamma_{ij}^k\}$ .
- (ii) The **forgetful Lie superalgebra of  $\mathfrak{g}$**  is defined as  $\mathcal{F}(\mathfrak{g}) = \{c_{ij}^k, \rho_{ij}^k, 0\}$ .

## Lemma

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$ . If  $\mathfrak{g} \rightarrow \mathfrak{h}$ , then

- (i)  $\text{ab}(\mathfrak{g}) \rightarrow \text{ab}(\mathfrak{h})$ .
- (ii)  $\mathcal{F}(\mathfrak{g}) \rightarrow \mathcal{F}(\mathfrak{h})$ .

# Invariants in $\mathcal{LS}^{(m,n)}$

## Lemma

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$ . If  $\mathfrak{g} \rightarrow \mathfrak{h}$ , then the following relations must hold:

- ▶  $\dim(G \cdot \mathfrak{g}) > \dim(G \cdot \mathfrak{h})$   
 $(\dim(G \cdot \mathfrak{g}) = \dim(G) - \dim(\text{Der}(\mathfrak{g})))$ .
- ▶  $\dim(\mathfrak{g}^1)_i \geq \dim(\mathfrak{h}^1)_i$  for  $i \in \mathbb{Z}_2$ .
- ▶ If  $[\cdot, \cdot]_{\mathfrak{g}_1 \times \mathfrak{g}_1} \equiv 0$ , then  $[\cdot, \cdot]_{\mathfrak{h}_1 \times \mathfrak{h}_1} \equiv 0$ .

# Invariants in $\mathcal{LS}^{(m,n)}$

## Lemma

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$ . If  $\mathfrak{g} \rightarrow \mathfrak{h}$ , then the following relations must hold:

▶  $\dim(G \cdot \mathfrak{g}) > \dim(G \cdot \mathfrak{h})$

$$(\dim(G \cdot \mathfrak{g}) = \dim(G) - \dim(\text{Der}(\mathfrak{g}))).$$

▶  $\dim(\mathfrak{g}^1)_i \geq \dim(\mathfrak{h}^1)_i$  for  $i \in \mathbb{Z}_2$ .

▶ If  $[\cdot, \cdot]_{\mathfrak{g}_1 \times \mathfrak{g}_1} \equiv 0$ , then  $[\cdot, \cdot]_{\mathfrak{h}_1 \times \mathfrak{h}_1} \equiv 0$ .

# Invariants in $\mathcal{LS}^{(m,n)}$

## Lemma

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$ . If  $\mathfrak{g} \rightarrow \mathfrak{h}$ , then the following relations must hold:

▶  $\dim(G \cdot \mathfrak{g}) > \dim(G \cdot \mathfrak{h})$

$$(\dim(G \cdot \mathfrak{g}) = \dim(G) - \dim(\text{Der}(\mathfrak{g}))).$$

▶  $\dim(\mathfrak{g}^1)_i \geq \dim(\mathfrak{h}^1)_i$  for  $i \in \mathbb{Z}_2$ .

▶ If  $[\cdot, \cdot]_{\mathfrak{g}_1 \times \mathfrak{g}_1} \equiv 0$ , then  $[\cdot, \cdot]_{\mathfrak{h}_1 \times \mathfrak{h}_1} \equiv 0$ .

# Invariants in $\mathcal{LS}^{(m,n)}$

## Lemma

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$ . If  $\mathfrak{g} \rightarrow \mathfrak{h}$ , then the following relations must hold:

- ▶  $\dim(G \cdot \mathfrak{g}) > \dim(G \cdot \mathfrak{h})$   
 $(\dim(G \cdot \mathfrak{g}) = \dim(G) - \dim(\text{Der}(\mathfrak{g})))$ .
- ▶  $\dim(\mathfrak{g}^1)_i \geq \dim(\mathfrak{h}^1)_i$  for  $i \in \mathbb{Z}_2$ .
- ▶ If  $[\cdot, \cdot]_{\mathfrak{g}_1 \times \mathfrak{g}_1} \equiv 0$ , then  $[\cdot, \cdot]_{\mathfrak{h}_1 \times \mathfrak{h}_1} \equiv 0$ .



# Invariants in $\mathcal{L}\mathcal{S}^{(m,n)}$

►  $\dim(\text{Der}(\alpha, \beta, \gamma))_i(\mathfrak{g}) \leq \dim(\text{Der}(\alpha, \beta, \gamma))_i(\mathfrak{h})$ , for  $i \in \mathbb{Z}_2$ .

(  $D \in \text{Der}(\alpha, \beta, \gamma)(\mathfrak{g})_i$  if  $\alpha D(\llbracket x, y \rrbracket) = \beta \llbracket D(x), y \rrbracket + (-1)^{i|x|} \gamma \llbracket x, D(y) \rrbracket$ ).

# The Variety $\mathcal{LS}^{(2,2)}$

Lie algebras of dimension 2. There exist, up to isomorphism, two Lie algebras of dimension 2.

- ▶ The abelian Lie algebra  $\mathfrak{a}_0$ .
- ▶ The affine Lie algebra  $\mathfrak{a}_1$ , ( $[e_1, e_2] = e_1$ ).

It follows that

$$\mathfrak{a}_1 \rightarrow \mathfrak{a}_0$$

Remark

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$  such that  $\mathfrak{g}_0 = \mathfrak{a}_0$ , and  $\mathfrak{h}_0 = \mathfrak{a}_1$ , then

$$\mathfrak{g} \not\cong \mathfrak{h}$$

# The Variety $\mathcal{LS}^{(2,2)}$

Lie algebras of dimension 2. There exist, up to isomorphism, two Lie algebras of dimension 2.

- ▶ The abelian Lie algebra  $\mathfrak{a}_0$ .
- ▶ The affine Lie algebra  $\mathfrak{a}_1$ , ( $[e_1, e_2] = e_1$ ).

It follows that

$$\mathfrak{a}_1 \rightarrow \mathfrak{a}_0$$

Remark

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$  such that  $\mathfrak{g}_0 = \mathfrak{a}_0$ , and  $\mathfrak{h}_0 = \mathfrak{a}_1$ , then

$$\mathfrak{g} \not\cong \mathfrak{h}$$

# The Variety $\mathcal{LS}^{(2,2)}$

Lie algebras of dimension 2. There exist, up to isomorphism, two Lie algebras of dimension 2.

- ▶ The abelian Lie algebra  $\mathfrak{a}_0$ .
- ▶ The affine Lie algebra  $\mathfrak{a}_1$ , ( $[e_1, e_2] = e_1$ ).

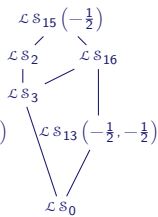
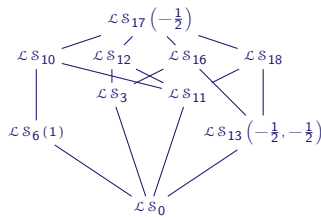
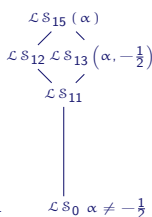
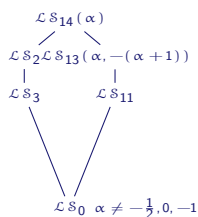
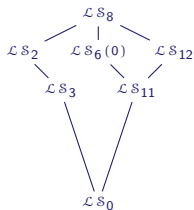
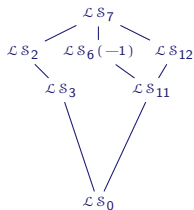
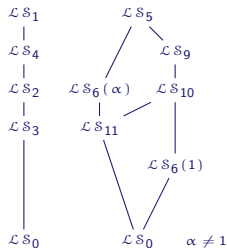
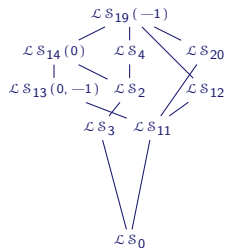
It follows that

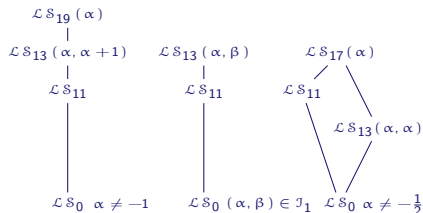
$$\mathfrak{a}_1 \rightarrow \mathfrak{a}_0$$

## Remark

Let  $\mathfrak{g}, \mathfrak{h} \in \mathcal{LS}^{(m,n)}$  such that  $\mathfrak{g}_0 = \mathfrak{a}_0$ , and  $\mathfrak{h}_0 = \mathfrak{a}_1$ , then

$$\mathfrak{g} \not\cong \mathfrak{h}$$

Hasse Diagrams in  $\mathcal{LS}(2, 2)$ 

Hasse Diagrams in  $\mathcal{LS}^{(2,2)}$ 

where  $\mathcal{J}_1 = \left\{ (\alpha, \beta) \left| \begin{array}{l} \alpha \neq -\frac{1}{2}, \beta, \beta+1, -(\beta+1), \text{ and} \\ \beta \neq -\frac{1}{2}, \alpha, \alpha+1, -(\alpha+1) \end{array} \right. \right\}$ .

Orbits in  $\mathcal{LS}^{(2,2)}$ 

The orbit closures in the variety  $\mathcal{LS}^{(2,2)}$  are as follows:

$\mathfrak{g}$	$\overline{G \cdot \mathfrak{g}}$
$\mathcal{LS}_0$	$\mathcal{LS}_0$
$\mathcal{LS}_1$	$\mathcal{LS}_1, \mathcal{LS}_2, \mathcal{LS}_3, \mathcal{LS}_4, \mathcal{LS}_0$
$\mathcal{LS}_2$	$\mathcal{LS}_2, \mathcal{LS}_3, \mathcal{LS}_0$
$\mathcal{LS}_3$	$\mathcal{LS}_3, \mathcal{LS}_0$
$\mathcal{LS}_4$	$\mathcal{LS}_4, \mathcal{LS}_2, \mathcal{LS}_3, \mathcal{LS}_0$
$\mathcal{LS}_5$	$\mathcal{LS}_5, \mathcal{LS}_9, \mathcal{LS}_6(\alpha), \mathcal{LS}_{10}, \mathcal{LS}_{11}, \mathcal{LS}_0$
$\mathcal{LS}_6(\alpha), \alpha \neq 1$	$\mathcal{LS}_6(\alpha), \mathcal{LS}_{11}, \mathcal{LS}_0$
$\mathcal{LS}_6(1)$	$\mathcal{LS}_6(1), \mathcal{LS}_0$
$\mathcal{LS}_7$	$\mathcal{LS}_7, \mathcal{LS}_2, \mathcal{LS}_6(-1), \mathcal{LS}_{12}, \mathcal{LS}_3, \mathcal{LS}_{11}, \mathcal{LS}_0$
$\mathcal{LS}_8$	$\mathcal{LS}_8, \mathcal{LS}_2, \mathcal{LS}_6(0), \mathcal{LS}_{12}, \mathcal{LS}_3, \mathcal{LS}_{11}, \mathcal{LS}_0$
$\mathcal{LS}_9$	$\mathcal{LS}_9, \mathcal{LS}_{10}, \mathcal{LS}_{11}, \mathcal{LS}_6(1), \mathcal{LS}_0$
$\mathcal{LS}_{10}$	$\mathcal{LS}_{10}, \mathcal{LS}_{11}, \mathcal{LS}_6(1), \mathcal{LS}_0$
$\mathcal{LS}_{11}$	$\mathcal{LS}_{11}, \mathcal{LS}_0$
$\mathcal{LS}_{12}$	$\mathcal{LS}_{12}, \mathcal{LS}_3, \mathcal{LS}_{11}, \mathcal{LS}_0$

Orbits in  $\mathcal{LS}^{(2,2)}$ 

$\mathcal{LS}_{13}(\alpha, \beta), \beta \neq \alpha$	$\mathcal{LS}_{13}(\alpha, \beta), \mathcal{LS}_{11}, \mathcal{LS}_0$
$\mathcal{LS}_{13}(\alpha, \alpha)$	$\mathcal{LS}_{13}(\alpha, \alpha), \mathcal{LS}_0$
$\mathcal{LS}_{14}(\alpha), \alpha \neq -\frac{1}{2}$	$\mathcal{LS}_{14}(\alpha), \mathcal{LS}_2, \mathcal{LS}_{13}(\alpha, -(\alpha + 1)), \mathcal{LS}_3, \mathcal{LS}_{11}, \mathcal{LS}_0$
$\mathcal{LS}_{15}(\alpha), \alpha \neq -\frac{1}{2}$	$\mathcal{LS}_{15}(\alpha), \mathcal{LS}_{12}, \mathcal{LS}_{13}(\alpha, -\frac{1}{2}), \mathcal{LS}_{11}, \mathcal{LS}_0$
$\mathcal{LS}_{15}(-\frac{1}{2})$	$\mathcal{LS}_{15}(-\frac{1}{2}), \mathcal{LS}_2, \mathcal{LS}_{16}, \mathcal{LS}_3, \mathcal{LS}_{13}(-\frac{1}{2}, -\frac{1}{2}), \mathcal{LS}_0$
$\mathcal{LS}_{16}$	$\mathcal{LS}_{16}, \mathcal{LS}_3, \mathcal{LS}_{13}(-\frac{1}{2}, -\frac{1}{2}), \mathcal{LS}_0$
$\mathcal{LS}_{17}(\alpha), \alpha \neq -\frac{1}{2}$	$\mathcal{LS}_{17}(\alpha), \mathcal{LS}_{11}, \mathcal{LS}_{13}(\alpha, \alpha), \mathcal{LS}_0$
$\mathcal{LS}_{17}(-\frac{1}{2})$	$\mathcal{LS}_{17}(-\frac{1}{2}), \mathcal{LS}_{10}, \mathcal{LS}_{12}, \mathcal{LS}_{16}, \mathcal{LS}_{18}, \mathcal{LS}_3,$ $\mathcal{LS}_{11}, \mathcal{LS}_6(1), \mathcal{LS}_{13}(-\frac{1}{2}, -\frac{1}{2}), \mathcal{LS}_0$
$\mathcal{LS}_{18}$	$\mathcal{LS}_{18}, \mathcal{LS}_{11}, \mathcal{LS}_{13}(-\frac{1}{2}, -\frac{1}{2}), \mathcal{LS}_0$
$\mathcal{LS}_{19}(\alpha), \alpha \neq -1$	$\mathcal{LS}_{19}(\alpha), \mathcal{LS}_{13}(\alpha, \alpha + 1), \mathcal{LS}_{11}, \mathcal{LS}_0$
$\mathcal{LS}_{19}(-1)$	$\mathcal{LS}_{19}(-1), \mathcal{LS}_4, \mathcal{LS}_{20}, \mathcal{LS}_2, \mathcal{LS}_{12}, \mathcal{LS}_3, \mathcal{LS}_{11}, \mathcal{LS}_0$
$\mathcal{LS}_{20}$	$\mathcal{LS}_{20}, \mathcal{LS}_{11}, \mathcal{LS}_0$



# Muito obrigada!

isabel@cimat.mx

# The irreducible components of $\mathcal{LS}^{(2,2)}$

## Lemma

*If  $G$  is a connected algebraic group acting on a variety  $X$ , then the irreducible components of  $X$  are stable under the action of  $G$ . Moreover, the irreducible components of the variety  $X$  are closures of single orbits or closures of infinite families of orbits.*

# Irreducible components of $\mathcal{LS}^{(2,2)}$

## Definition

A Lie superalgebra  $\mathfrak{g} \in \mathcal{LS}^{(m,n)}$  is called rigid, if its orbit  $G \cdot \mathfrak{g}$  is open in  $\mathcal{LS}^{(m,n)}$ .

## Lemma

Let  $\mathfrak{g} \in \mathcal{LS}^{(m,n)}$ . If  $H^2(\mathfrak{g}, \mathfrak{g})_0 = 0$ , then  $\mathfrak{g}$  is rigid

## Remark

Every rigid superalgebra  $\mathfrak{g}$  determines an irreducible component of  $\mathcal{LS}^{(m,n)}$ .

# Irreducible components of $\mathcal{LS}^{(2,2)}$

## Definition

A Lie superalgebra  $\mathfrak{g} \in \mathcal{LS}^{(m,n)}$  is called rigid, if its orbit  $G \cdot \mathfrak{g}$  is open in  $\mathcal{LS}^{(m,n)}$ .

## Lemma

Let  $\mathfrak{g} \in \mathcal{LS}^{(m,n)}$ . If  $H^2(\mathfrak{g}, \mathfrak{g})_0 = 0$ , then  $\mathfrak{g}$  is rigid

## Remark

Every rigid superalgebra  $\mathfrak{g}$  determines an irreducible component of  $\mathcal{LS}^{(m,n)}$ .

# Irreducible components of $\mathcal{LS}^{(2,2)}$

## Definition

A Lie superalgebra  $\mathfrak{g} \in \mathcal{LS}^{(m,n)}$  is called rigid, if its orbit  $G \cdot \mathfrak{g}$  is open in  $\mathcal{LS}^{(m,n)}$ .

## Lemma

Let  $\mathfrak{g} \in \mathcal{LS}^{(m,n)}$ . If  $H^2(\mathfrak{g}, \mathfrak{g})_0 = 0$ , then  $\mathfrak{g}$  is rigid

## Remark

Every rigid superalgebra  $\mathfrak{g}$  determines an irreducible component of  $\mathcal{LS}^{(m,n)}$ .

# The irreducible components of $\mathcal{LS}^{(2,2)}$

## Theorem

*There are 3 rigid Lie superalgebras in  $\mathcal{LS}^{(2,2)}$*

$$\mathcal{LS}_{19}(-1), \quad \mathcal{LS}_1, \quad \mathcal{LS}_5.$$

## Corollary

*The variety  $\mathcal{LS}^{(2,2)}$  has at least four irreducible components.*

# The irreducible components of $\mathcal{LS}^{(2,2)}$

## Theorem

*There are 3 rigid Lie superalgebras in  $\mathcal{LS}^{(2,2)}$*

$$\mathcal{LS}_{19}(-1), \quad \mathcal{LS}_1, \quad \mathcal{LS}_5.$$

## Corollary

*The variety  $\mathcal{LS}^{(2,2)}$  has at least four irreducible components.*

# The irreducible components of $\mathcal{LS}^{(2,2)}$

## Conjecture

The irreducible components of the variety  $\mathcal{LS}^{(2,2)}$  are:

$$(i) \mathcal{C}_1 = \overline{G \cdot \mathcal{LS}_{19}(-1)},$$

$$(ii) \mathcal{C}_2 = \overline{G \cdot \mathcal{LS}_1},$$

$$(iii) \mathcal{C}_3 = \overline{G \cdot \mathcal{LS}_5},$$

$$(iv) \mathcal{C}_4 = \overline{\bigcup_{\alpha \neq -\frac{1}{2}} G \cdot \mathcal{LS}_{14}(\alpha)},$$

$$(v) \mathcal{C}_5 = \overline{\bigcup_{\alpha \neq -\frac{1}{2}} \mathcal{LS}_{15}(\alpha)},$$

$$(vi) \mathcal{C}_6 = \overline{\bigcup_{\alpha \neq -1} \mathcal{LS}_{19}(\alpha)},$$

$$(vii) \mathcal{C}_7 = \overline{\bigcup_{\alpha\beta} \mathcal{LS}_{13}(\alpha, \beta)}.$$